

Data-Parallel Programming without Arrays

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1 Introduction

Despite its overwhelming popularity, the array type has serious drawbacks for parallel programming. In brief, array algorithms are unsafe (subject to out-of-bounds errors), weakly compositional, and brittle to change. A generic functor approach solves these problems, resulting in a programming style that is safe and strongly compositional (for code reuse), while robustly describing infinite families of guaranteed-correct algorithmic variations [Elliott, 2017].

For CPU-based and (especially) hardware implementations, the generic functor style of programming can perform fairly well. GPUs and their supporting programming models, however, have a very strong bias toward array programming. In particular, they efficiently support only “flat” data parallelism, corresponding to computing over arrays of scalar values. For this reason, Guy Blelloch and others have investigated automatic flattening of nested data parallelism, although they kept the array as central data type.

This note describes a design for a programming interface isomorphic to the generic functor composition style and an implementation that maps to efficient (I hope!) GPU-style array computations. The generated computations are guaranteed safe from out-of-bound errors despite using unsafe array operations internally, and the programming model remains elegantly compositional and generic-friendly.

2 Arrays and functors

An array is a sort of memoized version of a function over a finite, linearly ordered domain, usually taken to be $\{0, \dots, n - 1\}$ for some n . Let’s assume that we have an efficient implementation of arrays, e.g., from the *vector* package [Leshchinskiy, 2017]:

```
type Vector a = ... -- Dynamically sized vectors
```

```
index :: Vector a → Int → a
```

```
...
```

This *Vector* type has two major drawbacks:

- It is unsafe, since `index v i` can be applied even when `i` is out of bounds. Although indices can be checked against a recorded size, client code might fail to do so properly and must deal with erroneous indexing when detected.
- It provides no compositional structure to guide algorithm design.

The first problem stems from `index v` being a *partial* function from *Int*. One can instead make indexing be a *total* function from an explicit type of bounded natural numbers, resulting in an interface like that of the *vector-sized* package [Hermaszewski and Gamari, 2017]:

```
type Vector n v -- Statically sized vectors
```

```
index :: Vector n v → Finite n → v
```

```
...
```

The type *Finite n* represents the natural numbers less than n , i.e., $\{0, \dots, n - 1\}$. With *Vector*, we at least have a chance of using the type-checker to catch index out-of-bounds errors. Since Haskell doesn’t yet have full

dependent types, n here is a *type-level* natural number [ref], and we have only weak support for automatically checked safety proofs.

The second problem is subtler. Array-based algorithms typically involve index arithmetic that obscures the essence of an algorithm, is difficult to get correct, and is usually not validated automatically (e.g., by type checking) [Elliott, 2017]. Index arithmetic can be seen as mediating between a more natural data structure (e.g., trees) and its underlying representation (arrays). Choosing a more suitable representation eliminates the encoding and decoding, revealing the essence of the algorithm. The more natural data structures often correspond to memoized forms of functions, with these memoized forms arising from a small algebra of functors, including product and composition of functors and the two corresponding identities [Hinze, 2000; Elliott, 2017].

Programming in the functor vocabulary retains safety while gaining a natural programming style, free of any index calculations. The functor style, however, moves us further from SIMD-style architectures—including GPUs—which work with flat, *Int*-indexed arrays.

We now come to the main idea of this paper. To combine the benefits of the functor style (safety and compositionality) and of the flat array style (fast execution on SIMD architectures), combine the functor *interface* with the sized vector *representation* to form a type of “flattened functors”:¹

```
newtype Flat f a = Flat (Vector |Rep f| a)
```

The $|\cdot|$ type family assigns cardinalities to types. The associated type $Rep\ f$ satisfies the property that $\forall a.f\ a \cong Rep\ f \rightarrow a$. In words, f is a “representable functor” isomorphic to functions from the associated domain type $Rep\ f$.² This associated type comes from the *Representable* class [Kmetz, 2018, *Data.Functor.Rep*], which also provides the isomorphism as a pair of methods:

```
class Representable f where
  type Rep f
  tabulate :: (Rep f → a) → f a
  index :: f a → (Rep f → a)
```

The idea here is to think in terms of a representable functor f but represent as $Flat\ f$, which is isomorphic, shown as follows:

$$\begin{aligned} & f\ a \\ \cong & \{ \text{the } Representable \text{ isomorphism} \} \\ & Rep\ f \rightarrow a \\ \cong & \{ \text{equal cardinality domains} \} \\ & Finite\ |Rep\ f| \rightarrow a \\ \cong & \{ \forall n.Rep\ (Vector\ n) = Finite\ n \} \\ & Vector\ |Rep\ f|\ a \\ \cong & \{ \text{definition of } Flat \} \\ & Flat\ f\ a \end{aligned}$$

We can define the isomorphism concretely as a pair of mutually-inverse functions between $f\ a$ and $Flat\ f\ a$. First, however, we’ll need to look at isomorphisms more generally and isomorphisms with *Finite* n in particular.

3 Isomorphisms

[Rethink the order of subsections below.]

3.1 Basic isomorphisms

An isomorphism between types a and b is witnessed by a pair of functions $f :: a \rightarrow b$ and $f' :: b \rightarrow a$ such that $f \circ f' = id$ and $f' \circ f = id$.³

¹[Consider an intermediate step of using a type alias: `type Flat f a = Vector (Card (Rep f)) a`. We wouldn’t get an infinite family of correct algorithms as in generic parallel programming, but we still get safety.]

²[Refer also to “Naperian functors”.]

³The “ \cong ” symbol here is a data constructor, so an $a \cong_k b$ has a field of type $a \rightarrow b$ and another of type $b \rightarrow a$.

data $a \cong b = (a \rightarrow b) \rightleftharpoons (b \rightarrow a)$

This definition extends beyond functions to any category:

data $a \cong_k b = (a \text{ 'k' } b) \rightleftharpoons (b \text{ 'k' } a)$

Then (\cong) then becomes a simple specialization:

type $a \cong b = a \cong_{(\rightarrow)} b$

Although arrow inversion is not computable, we can still use it in a *specification* that relates arrows (e.g., functions) in k to arrows in (\cong_k) :

$iso :: (a \text{ 'k' } b) \rightarrow a \cong_k b$ -- non-computable specification
 $iso f = f \rightleftharpoons f^{-1}$

It will sometimes be convenient to extract the halves of an isomorphism:

$isoFwd :: a \cong_k b \rightarrow (a \text{ 'k' } b)$
 $isoFwd (f \rightleftharpoons _) = f$

$isoRev :: a \cong_k b \rightarrow (b \text{ 'k' } a)$
 $isoRev (_ \rightleftharpoons f') = f'$

Inversion is trivially definable for (\cong_k) :

$inv :: a \cong_k b \rightarrow b \cong_k a$
 $inv (f \rightleftharpoons f') = f' \rightleftharpoons f$

We will sometimes need not just isomorphisms, but *natural isomorphisms*:

type $f \cong g = \forall a. f a \cong g a$

3.2 Composing isomorphisms

We will use *iso* to specify operations on $a \cong_k b$ and calculate correct implementations of those operations.

Theorem 1 (Proved in Appendix A.1). Given the instance definitions in Figure 1, *iso* is a homomorphism with respect to each of the instantiated classes.^{4,5}

It will also be convenient to specialize the bifunctor operations from Figure 1 into one-sided versions, as shown in Figure 2.

3.3 Arrow isomorphisms

Although Figure 1 defines instances of many categorical operations for (\cong_k) , it omits some important classes, due to non-invertibility:⁶

class *MonoidalP* $k \Rightarrow$ *Cartesian* k **where**

$exl :: (a \times b) \text{ 'k' } a$

$exr :: (a \times b) \text{ 'k' } b$

class *MonoidalS* $k \Rightarrow$ *Cocartesian* k **where**

$inl :: a \text{ 'k' } (a + b)$

⁴[Try combining six classes into three (*Associative*, *Braided*, and *Monoidal*), e.g., **class** *Braided* $k (\odot)$ **where** $swap :: (a \odot b) \text{ 'k' } (b \odot a)$.]

⁵[Find a different symbol for (\rightleftharpoons) so as not to clash with Haskell's use for constrained polymorphism.]

⁶The projections *exl* and *exr* fail surjectivity, while *inl*, *inr*, and *apply* fail injectivity. [Do isomorphisms *curry* and *uncurry* into isomorphisms?]

<p>class <i>Category</i> <i>k</i> where <i>id</i> :: $a \text{ 'k' } a$ $(\circ) :: (b \text{ 'k' } c) \rightarrow (a \text{ 'k' } b) \rightarrow (a \text{ 'k' } c)$</p> <p>class <i>AssociativeP</i> <i>k</i> where <i>rassocP</i> :: $((a \times b) \times c) \text{ 'k' } (a \times (b \times c))$ <i>lassocP</i> :: $(a \times (b \times c)) \text{ 'k' } ((a \times b) \times c)$</p> <p>class <i>BraidedP</i> <i>k</i> where <i>swapP</i> :: $(a \times b) \text{ 'k' } (b \times a)$</p> <p>class <i>MonoidalP</i> <i>k</i> where $(\times) :: (a \text{ 'k' } c) \rightarrow (b \text{ 'k' } d)$ $\rightarrow ((a \times b) \text{ 'k' } (c \times d))$</p> <p>class <i>AssociativeS</i> <i>k</i> where <i>rassocS</i> :: $((a + b) + c) \text{ 'k' } (a + (b + c))$ <i>lassocS</i> :: $(a + (b + c)) \text{ 'k' } ((a + b) + c)$</p> <p>class <i>BraidedS</i> <i>k</i> where <i>swapS</i> :: $(a + b) \text{ 'k' } (b + a)$</p> <p>class <i>MonoidalS</i> <i>k</i> where $(+)$:: $(a \text{ 'k' } c) \rightarrow (b \text{ 'k' } d)$ $\rightarrow ((a + b) \text{ 'k' } (c + d))$</p> <p>class <i>Closed</i> <i>k</i> where (\Rightarrow) :: $(d \text{ 'k' } c) \rightarrow (a \text{ 'k' } b)$ $\rightarrow ((c \Rightarrow a) \text{ 'k' } (d \Rightarrow b))$</p>	<p>instance <i>Category</i> <i>k</i> \Rightarrow <i>Category</i> (\cong_k) where <i>id</i> = <i>id</i> \Rightarrow <i>id</i> $(g \Rightarrow g') \circ (f \Rightarrow f') = (g \circ f) \Rightarrow (f' \circ g')$</p> <p>instance <i>AssociativeP</i> <i>k</i> \Rightarrow <i>AssociativeP</i> (\cong_k) where <i>lassocP</i> = <i>lassocP</i> \Rightarrow <i>rassocP</i> <i>rassocP</i> = <i>rassocP</i> \Rightarrow <i>lassocP</i></p> <p>instance <i>BraidedP</i> <i>k</i> \Rightarrow <i>BraidedP</i> (\cong_k) where <i>swapP</i> = <i>swapP</i> \Rightarrow <i>swapP</i></p> <p>instance <i>MonoidalP</i> <i>k</i> \Rightarrow <i>MonoidalP</i> (\cong_k) where $(f \Rightarrow f') \times (g \Rightarrow g') = (f \times g) \Rightarrow (f' \times g')$</p> <p>instance <i>AssociativeS</i> <i>k</i> \Rightarrow <i>AssociativeS</i> (\cong_k) where <i>lassocS</i> = <i>lassocS</i> \Rightarrow <i>rassocS</i> <i>rassocS</i> = <i>rassocS</i> \Rightarrow <i>lassocS</i></p> <p>instance <i>BraidedS</i> <i>k</i> \Rightarrow <i>BraidedS</i> (\cong_k) where <i>swapS</i> = <i>swapS</i> \Rightarrow <i>swapS</i></p> <p>instance <i>MonoidalS</i> <i>k</i> \Rightarrow <i>MonoidalS</i> (\cong_k) where $(f \Rightarrow f') + (g \Rightarrow g') = (f + g) \Rightarrow (f' + g')$</p> <p>instance <i>Closed</i> <i>k</i> \Rightarrow <i>Closed</i> (\cong_k) where $(p \Rightarrow p') \Rightarrow (q \Rightarrow q') = (p \Rightarrow q) \Rightarrow (p' \Rightarrow q')$</p>
--	--

Figure 1: Isomorphisms (calculated in Appendix A.1, specified by *iso* as homomorphism)

```

first :: MonoidalP k => (a 'k' c) -> ((a x b) 'k' (c x b))
first f = f x id

second :: MonoidalP k => (b 'k' d) -> ((a x b) 'k' (a x d))
second g = id x g

left :: MonoidalS k => (a 'k' c) -> ((a + b) 'k' (c + b))
left f = f + id

right :: MonoidalS k => (b 'k' d) -> ((a + b) 'k' (a + d))
right g = id + g

dom :: Closed k => (d 'k' c) -> ((c => a) 'k' (d => a))
dom f = f => id

cod :: Closed k => (a 'k' b) -> ((c => a) 'k' (c => b))
cod g = id => g

```

Figure 2: One-sided specializations of product, coproduct, and exponential bifunctors

$$\text{inr} :: b \text{ 'k' } (a + b)$$

class (*MonoidalP* k , *Closed* k) \Rightarrow *MonoidalClosed* k **where**
apply :: $((a \Rightarrow b) \times a) \text{ 'k' } b$
curry :: $((a \times b) \text{ 'k' } c) \rightarrow (a \text{ 'k' } (b \Rightarrow c))$
uncurry :: $(a \text{ 'k' } (b \Rightarrow c)) \rightarrow ((a \times b) \text{ 'k' } c)$

These *Cartesian* and *Cocartesian* instances give rise to two useful derived operations:

$$\begin{aligned} (\Delta) &:: \text{Cartesian } k \Rightarrow (a \text{ 'k' } c) \rightarrow (a \text{ 'k' } d) \rightarrow (a \rightarrow (c \times d)) \\ (\nabla) &:: \text{Cocartesian } k \Rightarrow (c \text{ 'k' } a) \rightarrow (d \text{ 'k' } a) \rightarrow ((c + d) \text{ 'k' } a) \end{aligned}$$

In uncurried form,

$$\begin{aligned} \text{fork} &:: \text{Cartesian } k \Rightarrow (a \text{ 'k' } c) \times (a \text{ 'k' } d) \rightarrow (a \rightarrow (c \times d)) \\ \text{fork} &= \text{uncurry } (\Delta) \\ \text{join} &:: \text{Cocartesian } k \Rightarrow (c \text{ 'k' } a) \times (d \text{ 'k' } a) \rightarrow ((c + d) \text{ 'k' } a) \\ \text{join} &= \text{uncurry } (\nabla) \end{aligned}$$

These uncurried versions have inverses:

$$\begin{aligned} \text{unfork} &:: \text{Cartesian } k \Rightarrow (a \text{ 'k' } c) \times (a \text{ 'k' } d) \rightarrow (a \rightarrow (c \times d)) \\ \text{unfork } f &= (\text{exl} \circ f, \text{exr} \circ f) \\ \text{unjoin} &:: \text{Cocartesian } k \Rightarrow (c \text{ 'k' } a) \times (d \text{ 'k' } a) \rightarrow ((c + d) \text{ 'k' } a) \\ \text{unjoin } f &= (f \circ \text{inl}, f \circ \text{inr}) \end{aligned}$$

Lemma 2 (Proved in Appendix A.2). *fork* and *unfork* are inverses, as are *join* and *unjoin*.

We can thus package these pairs of inverses into isomorphisms:

$$\begin{aligned} \text{forkIso} &:: \text{Cocartesian } k \Rightarrow (a \text{ 'k' } c) \times (a \text{ 'k' } d) \cong (a \text{ 'k' } (c \times d)) \\ \text{forkIso} &= \text{fork} \Leftarrow \text{unfork} \\ \text{joinIso} &:: \text{Cartesian } k \Rightarrow (c \text{ 'k' } a) \times (d \text{ 'k' } a) \cong ((c + d) \text{ 'k' } a) \\ \text{joinIso} &= \text{join} \Leftarrow \text{unjoin} \end{aligned}$$

Likewise, *curry* and *uncurry* are always inverses:

$$\begin{aligned} \text{curryIso} &:: \text{MonoidalClosed } k \Rightarrow ((a \times b) \text{ 'k' } c) \cong (a \text{ 'k' } (b \rightarrow c)) \\ \text{curryIso} &= \text{curry} \Leftarrow \text{uncurry} \end{aligned}$$

3.4 Natural number isomorphisms

The notions of cardinality and isomorphism are tightly connected. Georg Cantor defined cardinality in terms of injections and isomorphisms [ref]. In particular, $|A| \leq |B|$ exactly when there is an injection from A to B , and $|A| = |B|$ exactly when there is a bijection from A to B . These definitions apply not only to finite sets and so laid the foundation for comparing cardinalities of infinite (even uncountably infinite) set, including Cantor's seminal result that there are strictly more real numbers than natural numbers.

Cardinality also relates the notions of sums, products, and exponentials on sets to sums, products, and exponentials on natural numbers:⁷

$$\begin{aligned} |a + b| &= |a| + |b| \\ |a \times b| &= |a| \times |b| \\ |a \uparrow b| &= |a| \uparrow |b| \end{aligned}$$

⁷[Either complete or remove the discussion of exponentials.]

```

type KnownNat2 m n = (KnownNat m, KnownNat n)

finU1 :: 0 ≅ Finite 0
finU1 = combineZero ⇔ separateZero

finPar1 :: 1 ≅ Finite 1
finPar1 = combineOne ⇔ separateOne

finSum :: KnownNat2 m n ⇒ Finite m + Finite n ≅ Finite (m + n)
finSum = combineSum ⇔ separateSum

finProd :: KnownNat2 m n ⇒ Finite m × Finite n ≅ Finite (m × n)
finProd = combineProd ⇔ separateProd

finExp :: KnownNat2 m n ⇒ Finite m ↑ Finite n ≅ Finite (m ↑ n)
finExp = combineExp ⇔ separateExp

-- ...

```

Figure 3: Isomorphisms involving *Finite*

where “ \uparrow ” refers to exponentiation on types in the LHS and on numbers in the RHS; and $a \uparrow b$ on types is more commonly written as “ $b \rightarrow a$ ” or “ $b \Rightarrow a$ ” (“exponentials” or “internal homs”). Let’s focus on finite sets, and particularly *Finite* n , i.e., the natural numbers $\{0, \dots, n - 1\}$, reasoning as follows:

$$\begin{aligned}
& |Finite (m + n)| \\
&= \{ \text{defining property of } Finite \} \\
&\quad m + n \\
&= \{ \text{defining property of } Finite \} \\
&\quad |Finite m| + |Finite n| \\
&= \{ \text{above} \} \\
&\quad |Finite m + Finite n|
\end{aligned}$$

Likewise for products and exponentials as well as for 0 and 1. Summarizing,

$$\begin{aligned}
|Finite \quad \mathbf{0} \quad | &= |\mathbf{0}| \\
|Finite \quad \mathbf{1} \quad | &= |\mathbf{1}| \\
|Finite (m + n) | &= |Finite m + Finite n| \\
|Finite (m \times n) | &= |Finite m \times Finite n| \\
|Finite (m \uparrow n) | &= |Finite m \uparrow Finite n|
\end{aligned}$$

where $\mathbf{0}$ is the empty type, and $\mathbf{1}$ is the unit type (usually written “*Void*” and “ $()$ ” in Haskell). Equivalently,

$$\begin{aligned}
Finite \quad \mathbf{0} &\cong \mathbf{0} \\
Finite \quad \mathbf{1} &\cong \mathbf{1} \\
Finite (m + n) &\cong Finite m + Finite n \\
Finite (m \times n) &\cong Finite m \times Finite n \\
Finite (m \uparrow n) &\cong Finite m \uparrow Finite n
\end{aligned}$$

Figure 3 defines these isomorphisms for later use.⁸ Figure 4 defines the operations used to construct isomorphisms in Figure 3. These operations correspond to functionality in the *finite-typelits* package [mniip, 2017].⁹

⁸[Fill in for exponentiation. Also, I may want to reverse the sense of these isomorphisms. If so, change the code and then the paper.]

⁹[Explain some of the Haskellisms. Also my overloading of (+) and (×) for sum and product of natural numbers and types. I’ll also need to explain the *Finite* constructor. Maybe revisit my attempt to redefine the *Finite* type.]

```

combineZero :: 0 → Finite 0
combineZero = absurd

separateZero :: Finite 0 → 0
separateZero = error "no Finite 0" -- Revisit.

combineOne :: 1 → Finite 1
combineOne = const (Finite 0)

separateOne :: Finite 1 → 1
separateOne = const ()

combineSum :: ∀m n. KnownNat₂ m n ⇒ (Finite m + Finite n) → Finite (m + n)
combineSum (Left (Finite l)) = Finite l
combineSum (Right (Finite k)) = Finite (nat @m + k)

separateSum :: ∀m n. KnownNat₂ m n ⇒ Finite (m + n) → (Finite m + Finite n)
separateSum (Finite l) | l < m = Left (Finite l)
                    | otherwise = Right (Finite (l - m))

where
    m = nat @m

combineProd :: ∀m n. KnownNat₂ m n ⇒ (Finite m × Finite n) → Finite (m × n)
combineProd (Finite l, Finite k) = Finite (nat @n × l + k)

separateProd :: ∀m n. KnownNat₂ m n ⇒ Finite (m × n) → (Finite m × Finite n)
separateProd (Finite l) = (Finite q, Finite r) where (q, r) = l 'divMod' nat @n

```

Figure 4: Sum and product isomorphisms

Lemma 3. The functions defined in Figure 4 are pairs of inverses (*combineZero* with *separateZero*, etc), justifying their use in Figure 3.¹⁰

Another property will turn out to be very useful:

Lemma 4. The functions defined in Figure 4 are strictly monotonic.

Monotonic isomorphisms are also referred to as “order isomorphisms”. While there may be many isomorphisms between two types, for finite, linearly ordered types, there is only one order isomorphism.^{11,12} Together with invertibility, this monotonicity property thus *uniquely* determines the functions defined in Figure 4. The linear orderings assumed in these definitions agree with Haskell’s *Ord* type class and standard instances, in which left injections are smaller than right injections, and products are ordered lexicographically:

instance (*Ord a, Ord b*) \Rightarrow *Ord (a + b)* **where**

Left $a < \text{Left } a' = a < a'$

Left $a < \text{Right } b' = \text{True}$

Right $b < \text{Left } a' = \text{False}$

Right $b < \text{Right } b' = b < b'$

instance (*Ord a, Ord b*) \Rightarrow *Ord (a × b)* **where**

$(a, b) < (a', b') = a < a' \vee (a = a' \wedge b < b')$

Lemma 5 (Proved in Appendix A.3). Monotonic functions on linear orders form a category that is monoidal under sums and products.^{13,14}

3.5 Some other useful isomorphisms

While Figures 1 and 2 shows how to construct and compose arrows with a standard vocabulary, we will also need some primitives, which we can easily build whenever we have a pair of inverses. We’ve already seen one example in Section 2, namely the representability isomorphism:

```
repIso :: Representable f  $\Rightarrow$  f a  $\cong$  (Rep f  $\rightarrow$  a)
repIso = index  $\rightleftharpoons$  tabulate
```

Another example is found in the *Newtype* class from the package *newtype-generics* [Jahandarie et al., 2018]:

```
class Newtype n where
  type O n
  pack  :: O n  $\rightarrow$  n
  unpack :: n  $\rightarrow$  O n
```

This class serves as a shared interface for the isomorphism between a **newtype**-defined data type and its underlying representation. We can wrap up instances:

```
newIso :: Newtype n  $\Rightarrow$  n  $\cong$  O n
newIso = unpack  $\rightleftharpoons$  pack
```

Closely related to *Newtype* is the *Coercible* class, which provides a way to perform safe, zero-cost conversions between types that share a common underlying representation [Breitner et al., 2014]. The safe coercion primitive is

```
coerce :: Coercible a b  $\Rightarrow$  a  $\rightarrow$  b
```

¹⁰[Can I calculate half of these functions from the others? The *combineX* functions are simpler, so start with them.]

¹¹Proof sketch: the smallest value of one type must map to the smallest of the other, the next smallest to the next smallest, etc.

¹²[In what other settings are order isomorphisms unique? At least for well-ordered sets [proof].]

¹³[Move this lemma to a later section, and expand it.]

¹⁴[What about under exponentials?]

Instances of the *Coercible* class are synthesized automatically as needed by the compiler. One source of these instances is **newtype** definitions, but others include congruence rules so that, for instance, if *Coercible a b* then *Coercible (f a) (f b)*, and so on for conversions involving arbitrarily nested **newtype** coercions. (There are some restrictions depending on the “role” of type parameters). Coercibility is also an equivalence relation (reflexive, symmetric, and transitive). Packaging as an isomorphism is straightforward:

$$\begin{aligned} \text{coerceIso} &:: \text{Coercible } a \ b \Rightarrow a \cong b \\ \text{coerceIso} &= \text{coerce} \Leftarrow \text{coerce} \end{aligned}$$

While *coerceIso* is much more flexible, *newIso* requires fewer type annotations.

3.6 Reindexing representable functors

Let’s now use our isomorphism vocabulary to form *reindexing* isomorphisms. Given representable functors *f* and *g*, suppose we have an isomorphism $h :: \text{Rep } g \cong \text{Rep } f$, converting between indices of *g* and *f*. Then *f* and *g* are also (naturally) isomorphic, witnessed as follows:¹⁵

$$\begin{aligned} \text{reindex} &:: (\text{Representable } f, \text{Representable } g) \Rightarrow (\text{Rep } g \cong \text{Rep } f) \rightarrow (f \cong g) \\ \text{reindex } h &= \text{inv repIso} \circ \text{dom } h \circ \text{repIso} \end{aligned}$$

where *dom* is defined in Figure 2.¹⁶ The types involved:

$$\begin{aligned} \text{repIso} &:: f \ a \cong (\text{Rep } f \rightarrow a) \\ \text{dom } h &:: (\text{Rep } f \rightarrow a) \cong (\text{Rep } g \rightarrow a) \\ \text{inv repIso} &:: (\text{Rep } g \rightarrow a) \cong g \ a \end{aligned}$$

This reindexing isomorphism will be exactly what we need to allow us to program in the style of generic functors but implement via flat data parallelism for SIMD execution.

Exercise 6. Show that *reindex* is a contravariant functor, i.e., $\text{reindex } id = id$, and $\text{reindex } (k \circ h) = \text{reindex } h \circ \text{reindex } k$ whenever these equations are type-correct. (When might they not be type-correct?)

There are some generally useful representable functors defined in *GHC.Generics* [Magalhães et al., 2011], shown with their *Representable* instances [Kmett, 2018] in Figure 5.^{17,18}

3.7 Reshaping vectors

Figure 6 applies reindexing from Section 3.6 with index isomorphisms involving *Finite* from Section 3.4, recalling that $\text{Rep } (\text{Vector } n) = \text{Finite } n$. The RHSs of these isomorphisms involve the generic functor building blocks. The types involved:

$$\begin{aligned} \text{finU}_1 &:: \mathbf{0} \cong \text{Finite } 0 \\ &:: \text{Rep } U_1 \cong \text{Rep } (\text{Vector } 0) \\ \text{reindex finU}_1 &:: U_1 \cong \text{Vector } 0 \\ \\ \text{finPar}_1 &:: \mathbf{1} \cong \text{Finite } 1 \\ &:: \text{Rep } \text{Par}_1 \cong \text{Rep } (\text{Vector } 1) \\ \text{reindex finPar}_1 &:: \text{Par}_1 \cong \text{Vector } 1 \\ \\ \text{finSum} &:: \text{Finite } m + \text{Finite } n \cong \text{Finite } (m + n) \\ &:: \text{Rep } (\text{Vector } m) + \text{Rep } (\text{Vector } n) \cong \text{Rep } (\text{Vector } (m + n)) \end{aligned}$$

¹⁵[I think *reindex* is a contravariant functorial. I first made it covariant, but I think contravariant fits the intent better. It also saves me double inversion of *dom h*.]

¹⁶[Maybe note some specializations of *reindex* at this point, including $h = id$, $f = (\rightarrow) a$, and $g = (\rightarrow) b$. In these cases, $\text{dom } h = id$, $\text{repIso} = id$, and $\text{inv repIso} = id$, respectively.]

¹⁷[Drop a hint about why these definitions.]

¹⁸[Rewrite each *index* and *tabulate* pair via a single isomorphism than handles both elegantly? How to present nicely, considering that *Representable* has two methods instead of one isomorphism-valued method?]

```

newtype  $U_1$      $a = U_1$                 -- unit
newtype  $Par_1$    $a = Par_1 a$             -- singleton
data     $(f \times g) a = f a \times g a$  -- product
newtype  $(g \circ f) a = Comp_1 (g (f a))$  -- composition

instance Representable  $U_1$  where
  type Rep  $U_1 = \mathbf{0}$ 
  index  $U_1 = absurd$ 
  tabulate  $_ = U_1$ 

instance Representable  $Par_1$  where
  type Rep  $Par_1 = ()$ 
  index  $(Par_1 a) () = a$ 
  tabulate  $f = Par_1 (f ())$ 

instance (Representable  $f$ , Representable  $g$ )  $\Rightarrow$  Representable  $(f \times g)$  where
  type Rep  $(f \times g) = Rep f + Rep g$ 
  index  $(a \times \_)$  (Left  $i$ ) = index  $a i$ 
  index  $(\_ \times b)$  (Right  $j$ ) = index  $b j$ 
  tabulate  $f = tabulate (f \circ Left) \times tabulate (f \circ Right)$ 

instance (Representable  $f$ , Representable  $g$ )  $\Rightarrow$  Representable  $(g \circ f)$  where
  type Rep  $(g \circ f) = Rep g \times Rep f$ 
  index  $(Comp_1 gf) (j, i) = index (index gf j) i$ 
  tabulate =  $Comp_1 \circ tabulate \circ fmap \ tabulate \circ curry$ 

```

Figure 5: Some generic functors and their associated *Representable* instances

```

vec $U_1 :: Vector \mathbf{0} \cong U_1$ 
vec $U_1 = reindex finU_1$ 

vec $Par_1 :: Vector \mathbf{1} \cong Par_1$ 
vec $Par_1 = reindex finPar_1$ 

vec $Prod :: KnownNat_2 m n \Rightarrow Vector (m + n) \cong Vector m \times Vector n$ 
vec $Prod = reindex finSum$ 

vec $Comp :: KnownNat_2 m n \Rightarrow Vector (m \times n) \cong Vector m \circ Vector n$ 
vec $Comp = reindex finProd$ 

```

Figure 6: Reshaping vectors

$$\begin{aligned} &:: \text{Rep } (\text{Vector } m \times \text{Vector } n) \cong \text{Rep } (\text{Vector } (m + n)) \\ \text{reindex } \text{finSum} &:: \text{Vector } (m + n) \cong \text{Vector } m \times \text{Vector } n \\ \\ \text{finProd} &:: \text{Finite } m \times \text{Finite } n \cong \text{Finite } (m \times n) \\ &:: \text{Rep } (\text{Vector } m) \times \text{Rep } (\text{Vector } n) \cong \text{Rep } (\text{Vector } (m \times n)) \\ &:: \text{Rep } (\text{Vector } m \circ \text{Vector } n) \cong \text{Rep } (\text{Vector } (m \times n)) \\ \text{reindex } \text{finProd} &:: \text{Vector } (m \times n) \cong \text{Vector } m \circ \text{Vector } n \end{aligned}$$

In the forward direction, *vecProd* slices a vector into two pieces, while *vecComp* slices a vector into a two-dimensional array.^{19,20}

3.8 Finite isomorphisms

For each type a with finitely many distinct values n , we can form an isomorphism between a and *Finite* n (representing the natural numbers $\{0, \dots, n - 1\}$ and introduced briefly in Section 2). We will then use the latter as safe array indices.²¹

```
type KnownCard a = KnownNat |a|

class KnownCard a  $\Rightarrow$  HasFin a where
  type |a| :: Nat
  fin :: a  $\cong$  Finite |a|
```

The *KnownNat* constraint is part of GHC’s support for type-level natural numbers [ref]. Figure 7 shows *HasFin* instances for some standard types and type constructions.²² These instances come from a simple specification:

Lemma 7. Each *fin* defined in Figure 7 is an order isomorphism.

Proof. Follows from Lemmas 4 and 5. □

It will sometimes be convenient to extract the halves of the *fin* isomorphism:

```
toFin :: HasFin a  $\Rightarrow$  a  $\rightarrow$  Finite |a|
toFin = isoFwd fin

unFin :: HasFin a  $\Rightarrow$  Finite |a|  $\rightarrow$  a
unFin = isoRev fin
```

4 Working with flattened functors

Section 2 defined a type *Flat* f a and showed it to be isomorphic to f a for any representable functor f having a finite associated index type. The vocabulary defined above suffices to define this isomorphism concretely:

```
flat :: HasFlat f  $\Rightarrow$  f  $\cong$  Flat f
flat = inv newIso  $\circ$  inv repIso  $\circ$  dom (inv fin)  $\circ$  repIso
```

This definition mirrors the type isomorphism chain appearing in Section 2.

To make for simpler calculations, let’s now slightly refactor the definition of *Flat*. Let *Arr* a b be a type of “domain-indexed safe arrays”²³, indexed by a with elements in b :

```
newtype Arr a b = Arr (Vector |a| b)
```

We can easily redefine *Flat* via *Arr*:

¹⁹[Add another isomorphism for exponentiation.]

²⁰[Use these vector-resaping definitions as *specifications*, but at least allude an efficient, no-copy implementation.]

²¹[I think I use the terms “vector” and “array” interchangeably. Perhaps pick one and stick to it.]

²²[Add a *HasFin* ($a \rightarrow b$) instance.]

²³[Look for a different description and matching name.]

```

type KnownCard a = KnownNat |a|

class KnownCard a ⇒ HasFin a where
  type |a| :: Nat
  fin :: a ≅ Finite |a|

instance HasFin 0 where
  type |0| = 0
  fin = finU1

instance HasFin 1 where
  type |1| = 1
  fin = finPar1

instance KnownNat n ⇒ HasFin (Finite n) where
  type |Finite n| = n
  fin = id

instance (HasFin a, HasFin b) ⇒ HasFin (a + b) where
  type |a + b| = |a| + |b|
  fin = finSum ∘ (fin + fin)

instance (HasFin a, HasFin b) ⇒ HasFin (a × b) where
  type |a × b| = |a| × |b|
  fin = finProd ∘ (fin × fin)

```

Figure 7: *HasFin* instances

```

type Flat f = Arr (Rep f)

```

The type *Arr* *a* *b* is isomorphic to $a \rightarrow b$:

```

arrFun :: HasFin a ⇒ Arr a b ≅ (a → b)
arrFun = dom fin ∘ repIso ∘ newIso

```

Use this isomorphism to define a *Representable* instance such that $\text{repIso} = \text{arrFun}$:

```

instance HasFin a ⇒ Representable (Arr a) where
  type Rep (Arr a) = a
  index = isoFwd arrFun
  tabulate = isoRev arrFun

```

Consequently, for *Arr* *a*,

```

index :: HasFin a ⇒ Arr a b → (a → b)
index = isoFwd arrFun
      = dom toFin ∘ index ∘ unpack
      = λ(Arr xs) → index xs ∘ toFin

```

```

tabulate :: HasFin a ⇒ (a → b) → Arr a b
tabulate = isoRev arrFun
          = pack ∘ tabulate ∘ dom unFin
          = λf → Arr (tabulate (f ∘ unFin))

```

We can adapt the vector-resaping isomorphisms from Section 3.7 to reshape *Arr* instead, as shown in Figure 8.

Lemma 8 (Proved in Appendix A.4). Each of the definitions in Figure 8 is equal to (a type instance of) *reindex id*.

```

type KnownCard2 a b = (KnownCard a, KnownCard b)

arrU1 :: Arr 0 ≅ U1
arrU1 = vecU1 ∘ newIso

arrPar1 :: Arr 1 ≅ Par1
arrPar1 = vecPar1 ∘ newIso

arrProd :: KnownCard2 a b ⇒ Arr (a + b) ≅ Arr a × Arr b
arrProd = coerceIso ∘ vecProd ∘ newIso

arrComp :: KnownCard2 a b ⇒ Arr (a × b) ≅ Arr a ∘ Arr b
arrComp = coerceIso ∘ vecComp ∘ newIso

```

Figure 8: *Arr* reshaping isomorphisms

Note that the only operations besides the corresponding vector reshapers are *newIso* and *coerceIso*, which will likely vanish at compile time.^{24,25,26} The *arrFun* isomorphism does most of the work for *flat*:²⁷

```

flat :: HasFlat f ⇒ f a ≅ Flat f a
flat = reindex id
      = inv repIso ∘ repIso

toFlat :: HasFlat f ⇒ f a → Flat f a
toFlat = isoFwd flat
        = tabulate ∘ index

```

These last two definitions look like they would simplify to *id*, but they do not, because the argument and result types differ. This pattern occurs whenever converting between functors via a common index type (here *Rep f*).²⁸

Now, note that homomorphisms compose (into homomorphisms), so to guarantee that *toFlat* is homomorphic, it suffices to guarantee that *tabulate* or *index* on *f* is homomorphic. We will *assume* the latter as a reasonable expectation on the representable functors involved.²⁹

Theorem 9 (Proved in Appendix A.5). Given the instance definitions below, *tabulate* for *Arr a* is a homomorphism with respect to *Functor* and *Applicative*.³⁰

```

instance Functor (Arr a) where
  fmap h (Arr bs) = Arr (fmap h bs)

instance KnownCard a ⇒ Applicative (Arr a) where
  pure a = Arr (pure a)
  Arr fs <*> Arr xs = Arr (fs <*> xs)

```

In Haskell, these two instance definitions can be written more succinctly:

```

deriving instance Functor (Arr a)
deriving instance KnownCard a ⇒ Applicative (Arr a)

```

²⁴[Do they?]

²⁵[Move this paragraph and figure somewhere more sensible.]

²⁶[I think each of these *Arr* reshapers is a special case of *reindex id*. Prove and exploit.]

²⁷[Revisit this part, since *arrFun* is no longer apparent here.]

²⁸Give a name to *reindex id*, and use it here.

²⁹[Return to this assumption.]

³⁰[Hence *index* is as well. Explain somewhere clearly and simply that inverses of homomorphisms and compositions of homomorphisms are also homomorphisms.]

```

instance Foldable ((→) 0) where
  fold _ = ∅

instance Foldable ((→) 1) where
  fold as = as ()

instance (Foldable ((→) a), Foldable ((→) b)) ⇒ Foldable ((→) (a + b)) where
  fold as = fold (as ∘ Left) ⊕ fold (as ∘ Right)

instance (Foldable ((→) a), Foldable ((→) b)) ⇒ Foldable ((→) (a × b)) where
  fold as = fold (fold ∘ curry as)

instance KnownNat n ⇒ Foldable ((→) (Finite n)) where
  ...

```

Figure 9: Folding functions

What’s remarkable about these definitions is that the conversions between the index type a and its numeric counterpart $Finite\ |a|$ (via the fin isomorphism) have disappeared during calculation. The index type a therefore plays no role in the structure of the algorithms used for $fmap$, $pure$, and $\langle\&*\rangle$ on $Arr\ a$. As the instances above show, these operations are implemented directly as the corresponding operations on $Vector\ n$.³¹ Those vector operations correspond to what SIMD-style parallel processors—including GPUs—do best, namely map k -ary functions over k vectors of arguments. We will see that the structure of the algorithms used for other operations *does* depend on the functor f . By fixing the *Functor* and *Applicative* implementations always to use the full SIMD style, we exploit the high-performance parallelism of the GPU architecture. By varying the implementations of other classes (*Foldable* etc) according to choice of functor f , we embrace a variety of parallel algorithms for solving the same problem with different sequential-vs-parallel trade-offs.³²

5 Folds

While the *Functor* and *Applicative* operations correspond to fully parallel computations, folds do not. Let’s now examine how to structure them by a combination of sequential and parallel composition. An important requirement to keep in mind is that GPU-style architectures support “flat” data parallelism, i.e., sequential compositions of fully parallel passes [ref].

5.1 Folding functions

Unlike $fmap$, $pure$, and $\langle\&*\rangle$ (from *Functor* and *Applicative*), we will not simply delegate $fold$ on $Arr\ a$ (or $Flat\ f$) to the same operation on vectors. Instead, we will imitate folds on *functions*. The standard Haskell libraries do not define these instances, but they could, as shown in Figure 9.^{33,34} These instances reflect the view of a function $f :: a \rightarrow b$ as an a -indexed collection of b values. To avoid ambiguity, the index type a must linearly ordered, and the $fold$ definitions must respect that ordering. In particular, for $a + b$, $Left\ a < Right\ b$ for all a and b , and for $a \times b$, ordering is lexicographic, as in Section 3.4.

Another way to justify these instances is to relate them to *Foldable* instances on the representable functors isomorphic to these functions, as shown in Figure 10.³⁵ The reverse might be more satisfying, however,

³¹The instances also involve removing and adding the `newtype` wrapper (Arr), but even those simple operations disappear during compilation.

³²[I think there is a lovely principle here to be highlighted. Datatype-indexed families of generic parallel algorithms are great [say why], but they don’t operate on arrays and so are difficult to map well to flat data parallelism. The Arr (or $Flat$) data type retains the type-driven nature of the families of generic algorithms, while mapping well to flat data parallelism. Revisit Guy Blelloch’s flattening transformation to determine how my techniques relate to it.]

³³[Explain Haskellisms, especially $\rightarrow a$.]

³⁴[Start using “ Fun ” in place of \rightarrow when given only one argument.]

³⁵[State and prove a theorem here. Maybe specify by enumerating the inhabitants of each functor in index order into a list and then folding over the list.]

```

instance Foldable  $U_1$  where
  fold  $U_1 = \emptyset$ 

instance Foldable  $Par_1$  where
  fold  $(Par_1 a) = a$ 

instance (Foldable  $f$ , Foldable  $g$ )  $\Rightarrow$  Foldable  $(f \times g)$  where
  fold  $(fa \times ga) = fold\ fa \oplus fold\ ga$ 

instance (Foldable  $f$ , Foldable  $g$ )  $\Rightarrow$  Foldable  $(g \circ f)$  where
  fold  $(Comp_1\ gfa) = fold\ (fmap\ fold\ gfa)$ 

instance KnownNat  $n \Rightarrow$  Foldable  $(Vector\ n)$  where
  ...

```

Figure 10: Folding representable functors

calculating *Foldable* instances for representable functors by appealing to the instances on functions in Figure 9.³⁶

Note that in Haskell’s current *Foldable* class, a *fold* definition does not suffice for a complete instance definition, so the *fold* definitions in Figure 9 would have to be replaced or augmented by *foldMap* definitions. Semantically, $foldMap\ f = fold \circ fmap\ f$, and that equality could be captured as a default definition for *foldMap*, though currently it is not. This current situation is unfortunate for parallel SIMD performance. As mentioned above, *fmap f* is a pure SIMD operation and so every *f* application in *fmap f* can be evaluated in a single parallel pass (assuming sufficient hardware resources), to then be followed by a sequential composition of passes for the remaining *fold*. Taking *foldMap f* as primitive moves those *f* applications *into* the fold, where they are no longer all evaluated in parallel.³⁷

We will sometimes want to re-parametrize functions monotonically for convenient and efficient folding:

Lemma 10 (Proved in Appendix A.6). For types a and b and any *order isomorphism* $h :: a \rightarrow b$, *dom h* is a *Foldable* isomorphism, i.e., have $fold = fold \circ dom\ h$. (The LHS *fold* is on $a \rightarrow x$, while the RHS *fold* is on $b \rightarrow x$.)

We can generalize Lemma 10 to reindexing of representable functors:

Lemma 11 (Proved in Appendix A.7). For functors f and g and any *order isomorphism* $h :: Rep\ g \cong Rep\ f$,

$$fold \circ index = fold \circ index \circ isoFwd\ (reindex\ h :: f \cong g)$$

5.2 Folding flattened functors

[Maybe move function folds to an earlier section, so we can move the *Foldable (Arr a)* instances earlier.]

Theorem 9 in Section 4 gives simple instances of *Functor* and *Applicative* for *Arr a*, calculated from the usual specification that *tabulate* (or *index*) on *Arr a* is a homomorphism:

Theorem 12 (Proved in Appendix A.8). Given the following instance definition, *index* for *Arr a* is a *Foldable* homomorphism:

```

instance Foldable  $(Arr\ a)$  where
  fold = fold  $\circ$  unpack

```

Equivalently,

```

deriving instance Foldable  $(Arr\ a)$ 

```

³⁶[Maybe do some, and leave the rest for exercises.]

³⁷[Return to this point later.]

```

instance Foldable (Arr 0) where
  fold = fold ◦ isoFwd arrU1

instance Foldable (Arr 1) where
  fold = fold ◦ isoFwd arrPar1

instance (Foldable (Arr a), Foldable (Arr b), KnownCard2 a b) ⇒ Foldable (Arr (a + b)) where
  fold = fold ◦ isoFwd arrProd

instance (Foldable (Arr a), Foldable (Arr b), KnownCard2 a b) ⇒ Foldable (Arr (a × b)) where
  fold = fold ◦ isoFwd arrComp

```

Figure 11: Specialized and optimized *Foldable* instances for *Arr*

As with *Functor* and *Applicative*, this *Foldable* instance for *Arr a* simply defers to the corresponding instance for *Vector |a|*. Although this instance is correct, it is somewhat dissatisfying. If we defer all instances for *Arr a* to the corresponding instances for *Vector |a|*, then we will have achieved our goal of safety, but not of type-directed algorithm design.³⁸ For *Functor* and *Applicative*, the *Vector* instances are compelling in that they directly exploit SIMD-style architecture. Since *fold* is not a SIMD operation in itself (due to data dependencies), it must be decomposed into a pattern of SIMD computations with at least some sequentiality. An entirely sequential *fold* would have a much longer parallel computation time than necessary. Instead, we can use the specific nature of *a* (not just its cardinality) into account.³⁹

Theorem 13 (Proved in Appendix A.9). The specialized instance definitions in Figure 11 below agree with the general instance above. With these specialized definitions, therefore, *index* for *Arr a* is a *Foldable* homomorphism.^{40,41}

[Return to *fold* vs *foldMap f*. Maybe I should start with *foldMap f* and then explain (or better, *show*) how *fold ◦ fmap f* gives better parallelism.]

6 What else?

[

- Idea: use *foldMap f* at first, and then discover the loss of parallelism, motivating factoring *foldMap f = fold ◦ fmap f*.
- *LScan* and *FFT*. There might not be much direct value in this work for just *Functor*, *Applicative*, and *Foldable*, since vector-specific versions don't specialize for the first two and don't might not be worth varying for the latter. I think I'll have to tackle a whole new issue, which is how to *construct Arr a* in a compositional and functional manner but still map to efficient data-parallel code. I think the underlying implementation will imperatively update output arrays. I guess I'll have to manage non-interference proofs for parallel computations, hopefully in an elegantly rigorous way.
- In-place update.
- Add an isomorphism version of *fold/unfold*, given an algebra/coalgebra isomorphism. Are there interesting and/or useful examples of invertible algebras?

]

³⁸[Connect these remarks to an earlier discussion of goals.]

³⁹[Maybe *fold* is a poor use of this flexibility. It may be perfectly fine to have a single *fold* strategy based *only* on cardinality. On the other hand, *scan* and *fft* make good use of additional flexibility.]

⁴⁰[Resolve *fold* vs *foldMap f*.]

⁴¹[Maybe refactor: add a class with a method that chooses an order isomorphism for reindexing. Then I could give a single instance for *Foldable (Arr a)* that defers to the new class and method.]

7 Related work

- The flattening transformation for nested data parallelism.
- Reversible computing?
- [Gibbons, 2017]
- [Hinze and James, 2010]

A Proofs

A.1 Theorem 1

First, let's require that iso is a *functor*, i.e., a homomorphism for the *Category* interface shown in Figure 1. The corresponding homomorphism properties for iso :

$$id = iso \ id$$

$$iso \ g \circ iso \ f = iso \ (g \circ f)$$

Start with the id homomorphism, and simplify the RHS:

$$\begin{aligned}
 & iso \ id \\
 = & \{ \text{definition of } iso \} \\
 & id \rightleftharpoons id^{-1} \\
 = & \{ id \text{ is its own inverse (i.e., } id \circ id = id) \} \\
 & id \rightleftharpoons id
 \end{aligned}$$

The id homomorphism for iso is thus equivalent to

$$id = id \rightleftharpoons id$$

We can thus satisfy the homomorphism requirement by using this version of as a *definition*.

Next consider the (\circ) homomorphism and simplify the LHS:

$$\begin{aligned}
 & iso \ g \circ iso \ f \\
 = & \{ \text{definition of } iso \} \\
 & (g \rightleftharpoons g^{-1}) \circ (f \rightleftharpoons f^{-1})
 \end{aligned}$$

Then the RHS:

$$\begin{aligned}
 & iso \ (g \circ f) \\
 = & \{ \text{definition of } iso \} \\
 & (g \circ f) \rightleftharpoons (g \circ f)^{-1} \\
 = & \{ \text{property of inversion and composition} \} \\
 & (g \circ f) \rightleftharpoons (f^{-1} \circ g^{-1})
 \end{aligned}$$

The (\circ) homomorphism is thus equivalent to

$$((g \rightleftharpoons g^{-1}) \circ (f \rightleftharpoons f^{-1})) = (g \circ f \rightleftharpoons f^{-1} \circ g^{-1})$$

Now *strengthen* this requirement by generalizing from f^{-1} and g^{-1} to arbitrary f' and g' (having the required types):

$$((g \rightleftharpoons g') \circ (f \rightleftharpoons f')) = (g \circ f \rightleftharpoons f' \circ g')$$

This strengthened (hence sufficient) condition is also in solved form and so can be satisfied by definition.

We can set up and solve similar homomorphism equations for the operations of the other categorical classes, leading to the class instances in Figure 1. For instance, for *MonoidalP*, the crucial insight is as follows:

Lemma 14. The product, coproduct, and exponential bifunctors invert as follows:

$$\begin{aligned} (f \times g)^{-1} &= f^{-1} \times g^{-1} \\ (f + g)^{-1} &= f^{-1} + g^{-1} \\ (f \Rightarrow g)^{-1} &= f^{-1} \Rightarrow g^{-1} \end{aligned}$$

Proof:

$$\begin{aligned} &(f^{-1} \times g^{-1}) \circ (f \times g) \\ &= \{ (f \times g) \circ (h \times k) = (f \circ h) \times (g \circ k) \text{ [Gibbons, 2002, Section 1.5.1]} \} \\ &\quad f^{-1} \circ f \times g^{-1} \circ g \\ &= \{ \text{fundamental property of inverses} \} \\ &\quad id \times id \\ &= \{ \text{[Gibbons, 2002, Section 1.5.1]} \} \\ &\quad id \end{aligned}$$

Likewise $(f \times g) \circ (f^{-1} \times g^{-1}) = id$. Similarly for $f + g$, while $f \Rightarrow g$ differs slightly due to contravariance:

$$\begin{aligned} &(f^{-1} \Rightarrow g^{-1}) \circ (f \Rightarrow g) \\ &= \{ (f \Rightarrow g) \circ (h \Rightarrow k) = (h \circ f) \Rightarrow (g \circ k) \} \\ &\quad f \circ f^{-1} \Rightarrow g^{-1} \circ g \\ &= \{ \text{fundamental property of inverses} \} \\ &\quad id \Rightarrow id \\ &= \{ \text{[cite or prove]} \} \\ &\quad id \end{aligned}$$

□

A.2 Lemma 2

$\begin{aligned} &unfork \circ fork \\ &= \{ \eta\text{-expansion} \} \\ &\quad \lambda(f, g) \rightarrow unfork (fork (f, g)) \\ &= \{ \text{definition of } fork \} \\ &\quad \lambda(f, g) \rightarrow unfork (f \triangle g) \\ &= \{ \text{definition of } unfork \} \\ &\quad \lambda(f, g) \rightarrow (exl \circ (f \triangle g), exr \circ (f \triangle g)) \\ &= \{ \text{[Gibbons, 2002, Section 1.5.1]} \} \\ &\quad \lambda(f, g) \rightarrow (f, g) \\ &= \{ \text{definition of } id \text{ for functions} \} \\ &\quad id \end{aligned}$	$\begin{aligned} &unjoin \circ join \\ &= \{ \eta\text{-expansion} \} \\ &\quad \lambda(f, g) \rightarrow unjoin (join (f, g)) \\ &= \{ \text{definition of } join \} \\ &\quad \lambda(f, g) \rightarrow unjoin (f \nabla g) \\ &= \{ \text{definition of } unjoin \} \\ &\quad \lambda(f, g) \rightarrow ((f \nabla g) \circ inl, (f \nabla g) \circ inr) \\ &= \{ \text{[Gibbons, 2002, Section 1.5.2]} \} \\ &\quad \lambda(f, g) \rightarrow (f, g) \\ &= \{ \text{definition of } id \text{ for functions} \} \\ &\quad id \end{aligned}$
--	---

$$\begin{array}{l|l}
\begin{array}{l}
fork \circ unfork \\
= \{ \eta\text{-expansion} \} \\
\lambda f \rightarrow fork (unfork f) \\
= \{ \text{definition of } unfork \} \\
\lambda f \rightarrow fork (exl \circ f, exr \circ f) \\
= \{ \text{definition of } fork \} \\
\lambda f \rightarrow (exl \circ f) \triangle (exr \circ f) \\
= \{ [\text{Gibbons, 2002, Section 1.5.1}] \} \\
\lambda f \rightarrow (exl \triangle exr) \circ f \\
= \{ [\text{Gibbons, 2002, Section 1.5.1}] \} \\
\lambda f \rightarrow id \circ f \\
= \{ \text{property of } id \text{ and } (\circ) \} \\
\lambda f \rightarrow f \\
= \{ \text{definition of } id \text{ for functions} \} \\
id
\end{array}
&
\begin{array}{l}
join \circ unjoin \\
= \{ \eta\text{-expansion} \} \\
\lambda f \rightarrow join (unjoin f) \\
= \{ \text{definition of } unjoin \} \\
\lambda f \rightarrow join (f \circ inl, f \circ inr) \\
= \{ \text{definition of } join \} \\
\lambda f \rightarrow (f \circ inl) \nabla (f \circ inr) \\
= \{ [\text{Gibbons, 2002, Section 1.5.2}] \} \\
\lambda f \rightarrow f \circ (inl \nabla inr) \\
= \{ [\text{Gibbons, 2002, Section 1.5.2}] \} \\
\lambda f \rightarrow f \circ id \\
= \{ \text{property of } id \text{ and } (\circ) \} \\
\lambda f \rightarrow f \\
= \{ \text{definition of } id \text{ for functions} \} \\
id
\end{array}
\end{array}$$

A.3 Lemma 5

[To do. See my notes from 2018-08-01.]

A.4 Lemma 8

[See my notes from 2018-08-11. I'm looking for much simpler proofs.]

A.5 Theorem 9

[Add some explanation here.]

$$\begin{array}{l}
tabulate \circ fmap f \circ index \\
= \{ \text{definition of } tabulate \text{ and } index \text{ for } Arr \ a \} \\
pack \circ tabulate \circ dom \ unFin \circ fmap f \circ dom \ toFin \circ index \circ unpack \\
= \{ tabulate \circ dom \ unFin \text{ is a } Functor \text{ homomorphism} \} \\
pack \circ fmap f \circ unpack \\
\\
tabulate (pure a) \\
= \{ \text{definition of } tabulate \text{ for } Arr \ a \} \\
pack (tabulate (dom \ unFin (pure a))) \\
= \{ tabulate \circ dom \ unFin \text{ is an } Applicative \text{ homomorphism} \} \\
pack (pure a) \\
\\
tabulate (index fs <*> index xs) \\
= \{ \text{definition of } tabulate \text{ and } index \text{ for } Arr \ a \} \\
pack (tabulate (dom \ unFin (dom \ toFin (index (unpack fs)) <*> dom \ toFin (index (unpack xs))))) \\
= \{ tabulate \circ dom \ unFin \text{ is an } Applicative \text{ homomorphism} \} \\
pack (unpack fs <*> unpack xs)
\end{array}$$

A.6 Lemma 10

Proof.

$$\begin{array}{l}
fold \circ dom h \\
= \{ \eta\text{-expansion} \} \\
\lambda xs \rightarrow fold (dom h xs) \\
= \{ \text{definition of } dom \text{ on functions} \} \\
\lambda xs \rightarrow fold (xs \circ h)
\end{array}$$

[How to finish this proof? Maybe via a new lemma in Section 5.1. Still, I think I'll need a new angle in order to make general claims about folds on functions.] \square

Lemma 15. For any function $f :: u \rightarrow v$, $\text{dom } f$ is a *Functor* and *Applicative* homomorphism.

Proof.

$$\begin{aligned}
& \text{dom } f (\text{fmap } h \text{ } xs) \\
= & \{ \text{definition of } \text{fmap} \text{ on functions } \} \\
& \text{dom } f (h \circ xs) \\
= & \{ \text{definition of } \text{dom} \} \\
& (h \circ xs) \circ f \\
= & \{ \text{associativity of } (\circ) \} \\
& h \circ (xs \circ f) \\
= & \{ \text{definition of } \text{dom} \} \\
& h \circ \text{dom } f \text{ } xs \\
= & \{ \text{definition of } \text{fmap} \text{ on functions } \} \\
& \text{fmap } h (\text{dom } f \text{ } xs)
\end{aligned}$$

$$\begin{aligned}
& \text{dom } f (\text{pure } a) \\
= & \{ \text{definition of } \text{pure} \text{ on functions } \} \\
& \text{dom } f (\text{const } a) \\
= & \{ \text{definition of } \text{dom} \} \\
& \text{const } a \circ f \\
= & \{ \text{property of } \text{const} \text{ and } (\circ) \} \\
& \text{const } a \\
= & \{ \text{definition of } \text{pure} \text{ on functions } \} \\
& \text{pure } a
\end{aligned}$$

$$\begin{aligned}
& \text{dom } f (hs \langle * \rangle xs) \\
= & \{ \text{definition of } (\langle * \rangle) \text{ on functions } \} \\
& \text{dom } f (\lambda u \rightarrow hs \text{ } u \langle * \rangle xs \text{ } u) \\
= & \{ \text{definition of } \text{dom} \} \\
& (\lambda u \rightarrow hs \text{ } u \langle * \rangle xs \text{ } u) \circ f \\
= & \{ \text{definition of } (\circ) \text{ on functions } \} \\
& (\lambda u \rightarrow (hs (f \text{ } u)) (xs (f \text{ } u))) \\
= & \{ \text{definition of } (\circ) \text{ on functions } \} \\
& (\lambda u \rightarrow ((hs \circ f) \text{ } u) ((xs \circ f) \text{ } u)) \\
= & \{ \text{definition of } (\langle * \rangle) \text{ on functions } \} \\
& (hs \circ f) \langle * \rangle (xs \circ f) \\
= & \{ \text{definition of } \text{dom} \} \\
& \text{dom } f \text{ } hs \langle * \rangle \text{dom } f \text{ } xs
\end{aligned}$$

\square

A.7 Lemma 11

Proof.

$$\begin{aligned}
& \text{fold} \circ \text{index} \circ \text{isoFwd} (\text{reindex } h) \\
= & \{ \text{definition of } \text{reindex} \} \\
& \text{fold} \circ \text{index} \circ \text{isoFwd} (\text{inv repIso} \circ \text{dom } h \circ \text{repIso}) \\
= & \{ \text{definitions of } (\circ) \text{ on IsoT } k, \text{ inv, etc } \} \\
& \text{fold} \circ \text{index} \circ \text{tabulate} \circ \text{dom} (\text{isoFwd } h) \circ \text{index} \\
= & \{ \text{index} \circ \text{tabulate} = \text{id} \} \\
& \text{fold} \circ \text{dom} (\text{isoFwd } h) \circ \text{index}
\end{aligned}$$

$$= \{ \text{Lemma 10} \} \\ \text{fold} \circ \text{index}$$

□

A.8 Theorem 12

We want to show that $\text{fold} \circ \text{index} = \text{fold} \circ \text{unpack}$, where the equation is on $\text{Arr } a$. (The LHS fold is on $(\rightarrow) a$ and the RHS fold is on $\text{Vector } |a|$.)

Proof.

$$\text{fold} \circ \text{index} \\ = \{ \text{definition of } \text{index} \text{ for } \text{Arr } a \} \\ \text{fold} \circ \text{dom toFin} \circ \text{index} \circ \text{unpack} \\ = \{ \text{dom toFin} \circ \text{index} \text{ is a } \text{Foldable} \text{ homomorphism} \} \\ \text{fold} \circ \text{unpack}$$

The last step depends on dom toFin being a *Foldable* homomorphism, which follows from Theorem 7 and Lemma 11. □

A.9 Theorem 13

Proof. Let p be one of the *Arr*-reshaping isomorphisms in Figure 8. By Lemma 8, we know that $p = \text{reindex } h$ where h is monotonic (and in fact $h = \text{id}$).

$$\text{fold} \\ = \{ \text{definition of } \text{Foldable} \text{ instance (Figure 8)} \} \\ \text{fold} \circ \text{isoFwd} (\text{reindex } h) \\ = \{ \text{induction on the index type} \} \\ \text{fold} \circ \text{index} \circ \text{isoFwd} (\text{reindex } h) \\ = \{ \text{Lemma 11} \} \\ \text{fold} \circ \text{index}$$

□

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