

Compiling to categories

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Overloading

- Alternative interpretation of common vocabulary.
- Laws for modular reasoning.
- Doesn't apply to lambda, variables, and application.
- Instead, *eliminate* them.

Eliminating lambda

$$(\lambda p \rightarrow k) \quad \dashrightarrow \text{const } k$$

$$(\lambda p \rightarrow p) \quad \dashrightarrow \text{id}$$

$$(\lambda p \rightarrow u \ v) \quad \dashrightarrow \text{apply} \circ ((\lambda p \rightarrow u) \triangle (\lambda p \rightarrow v))$$

$$\begin{aligned} (\lambda p \rightarrow \lambda q \rightarrow u) &\dashrightarrow \text{curry } (\lambda(p, q) \rightarrow u) \\ &\dashrightarrow \text{curry } (\lambda r \rightarrow u [p := \text{fst } r, q := \text{snd } r]) \end{aligned}$$

Automate via a compiler plugin.

Examples

$sqr :: Num\ a \Rightarrow a \rightarrow a$

$sqr\ a = a * a$

$magSqr :: Num\ a \Rightarrow a \times a \rightarrow a$

$magSqr\ (a, b) = sqr\ a + sqr\ b$

$cosSinProd :: Floating\ a \Rightarrow a \times a \rightarrow a \times a$

$cosSinProd\ (x, y) = (cos\ z, sin\ z)$ **where** $z = x * y$

After λ -elimination:

$sqr = mulC \circ (id \triangle id)$

$magSqr = addC \circ (mulC \circ (exl \triangle exl) \triangle mulC \circ (exr \triangle exr))$

$cosSinProd = (cosC \triangle sinC) \circ mulC$

Abstract algebra for functions

Interface:

class *Category* *k* **where**

id :: *a* `k` *a*

(*o*) :: (*b* `k` *c*) → (*a* `k` *b*) → (*a* `k` *c*)

infixr 9 *o*

Laws:

$id \circ f \equiv f$

$g \circ id \equiv g$

$(h \circ g) \circ f \equiv h \circ (g \circ f)$

Products

Interface:

```
class Category  $k \Rightarrow \text{Cartesian } k$  where  
  type  $a \times_k b$   
   $exl :: (a \times_k b) \rightarrow k \rightarrow a$   
   $exr :: (a \times_k b) \rightarrow k \rightarrow b$   
   $(\Delta) :: (a \rightarrow k \rightarrow c) \rightarrow (a \rightarrow k \rightarrow d) \rightarrow (a \rightarrow k \rightarrow (c \times_k d))$   
  infixr 3  $\Delta$ 
```

Laws:

$$\begin{aligned} exl \circ (f \Delta g) &\equiv f \\ exr \circ (f \Delta g) &\equiv g \\ exl \circ h \Delta exr \circ h &\equiv h \end{aligned}$$

Coproducts

Dual to product.

```
class Category k  $\Rightarrow$  Cocartesian k where  
  type a  $+_k$  b  
  inl :: a `k` (a  $+_k$  b)  
  inr :: b `k` (a  $+_k$  b)  
  ( $\nabla$ ) :: (a `k` c)  $\rightarrow$  (b `k` c)  $\rightarrow$  ((a  $+_k$  b) `k` c)  
  infixr 2  $\nabla$ 
```

Laws:

$$(f \nabla g) \circ \text{inl} \quad \equiv f$$
$$(f \nabla g) \circ \text{inr} \quad \equiv g$$
$$h \circ \text{inl} \nabla h \circ \text{inr} \equiv h$$

Exponentials

First-class “functions” (morphisms):

```
class Cartesian k  $\Rightarrow$  CartesianClosed k where  
  type a  $\Rightarrow_k$  b  
  apply    :: ((a  $\Rightarrow_k$  b)  $\times_k$  a) `k` b  
  curry    :: ((a  $\times_k$  b) `k` c)  $\rightarrow$  (a `k` (b  $\Rightarrow_k$  c))  
  uncurry  :: (a `k` (b  $\Rightarrow_k$  c))  $\rightarrow$  ((a  $\times_k$  b) `k` c)
```

Laws:

$$\begin{aligned} \text{uncurry } (\text{curry } f) &\equiv f \\ \text{curry } (\text{uncurry } g) &\equiv g \\ \text{apply} \circ (\text{curry } f \circ \text{exl} \triangle \text{exr}) &\equiv f \end{aligned}$$

Misc operations

```
class NumCat k a where  
  negateC      :: a `k` a  
  addC, sub, mulC :: (a ×k a) `k` a  
  ...  
...
```

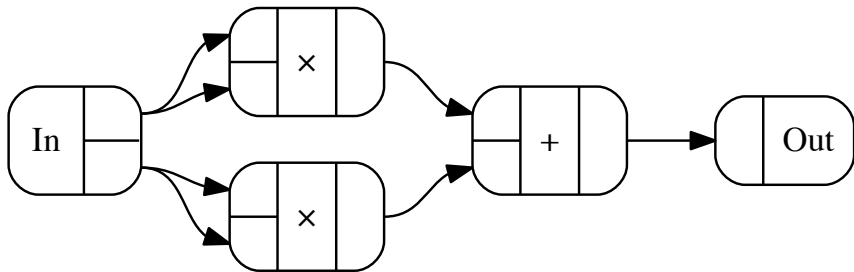
Changing interpretations

- We've eliminated lambdas and variables
- and replaced them with an algebraic vocabulary.
- What happens if we *replace* (\rightarrow) *with other instances?*
(Via compiler plugin.)

Computation graphs — example

$$\mathit{magSqr} (a, b) = \mathit{sqr} a + \mathit{sqr} b$$

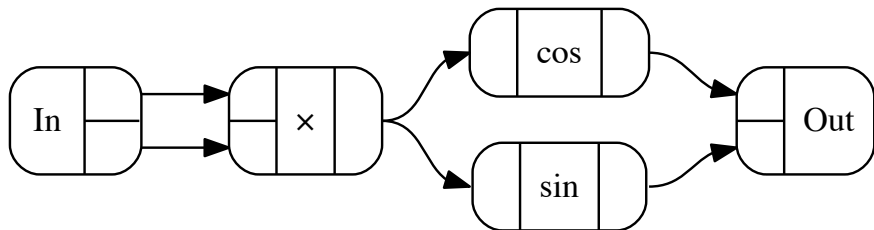
$$\mathit{magSqr} = \mathit{addC} \circ (\mathit{mulC} \circ (\mathit{exl} \triangle \mathit{exl}) \triangle \mathit{mulC} \circ (\mathit{exr} \triangle \mathit{exr}))$$



Computation graphs — example

$\text{cosSinProd}(x, y) = (\text{cos } z, \text{sin } z)$ **where** $z = x * y$

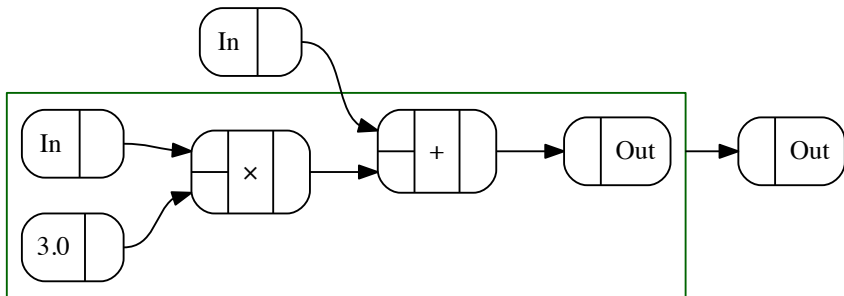
$\text{cosSinProd} = (\text{cosC} \triangle \text{sinC}) \circ \text{mulC}$



Computation graphs — example

$\lambda x y \rightarrow x + 3 * y$

$\text{curry} (\text{addC} \circ (\text{exl} \triangle \text{mulC} \circ (\text{const } 3.0 \triangle \text{exr})))$



Computation graphs — implementation sketch

```
newtype Graph a b = Graph (Ports a → GraphM (Ports b))
```

```
type GraphM = State (PortNum, [Comp])
```

```
data Comp = ∀ a b. Comp (Template a b) (Ports a) (Ports b)
```

```
data Template :: * → * → * where
```

```
  Prim      :: String → Template a b
```

```
  Subgraph :: Graph a b → Template () (a → b)
```

```
instance Category Graph where
```

```
  id = Graph return
```

```
  Graph g ∘ Graph f = Graph (g <=< f)
```

```
instance BoolCat Graph where
```

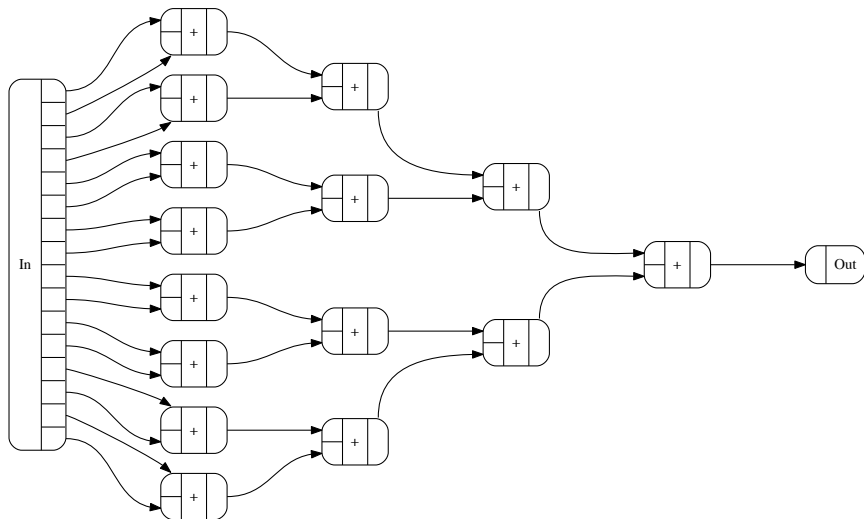
```
  notC = genComp "¬"
```

```
  andC = genComp "∧"
```

```
  orC  = genComp "∨"
```

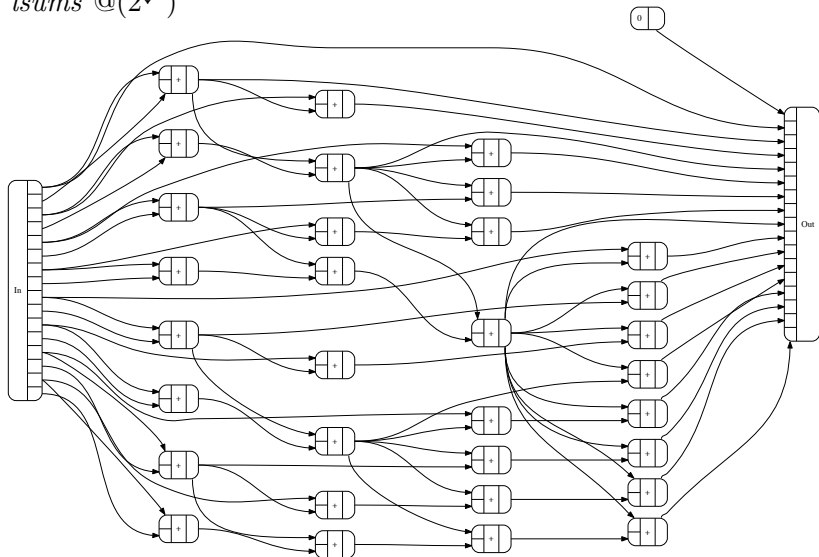
Computation graphs — fold

sum @($2^{\downarrow 4}$)



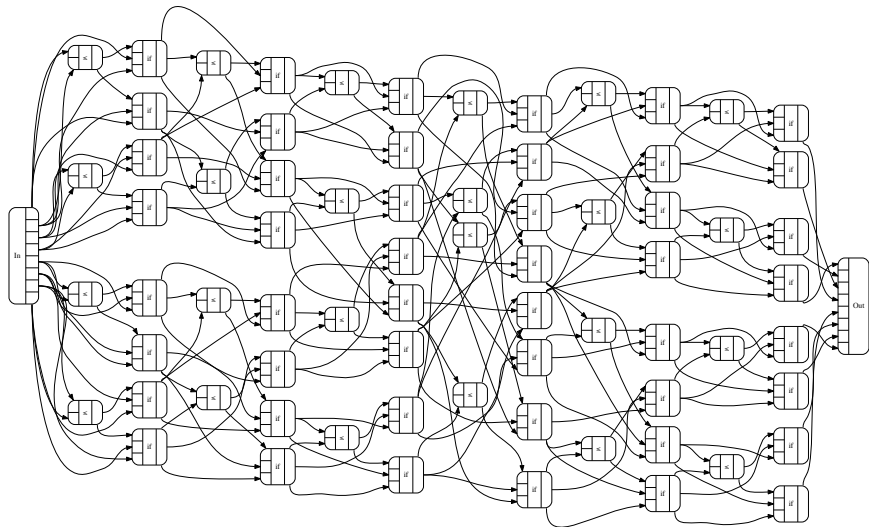
Computation graphs — scan

lsums @($2^{\downarrow 4}$)



Computation graphs — bitonic sort

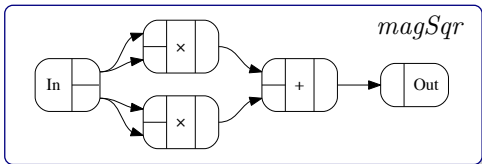
bitonic @($2^{\downarrow 3}$)



Compiling to hardware

Convert graphs to Verilog:

```
module magSqr (In_0, In_1, Out);  
  input [31:0] In_0;  
  input [31:0] In_1;  
  output [31:0] Out;  
  wire [31:0] Plus_I0;  
  wire [31:0] Times_I3;  
  wire [31:0] Times_I4;  
  assign Plus_I0 = Times_I3 + Times_I4;  
  assign Out = Plus_I0;  
  assign Times_I3 = In_0 * In_0;  
  assign Times_I4 = In_1 * In_1;  
endmodule
```



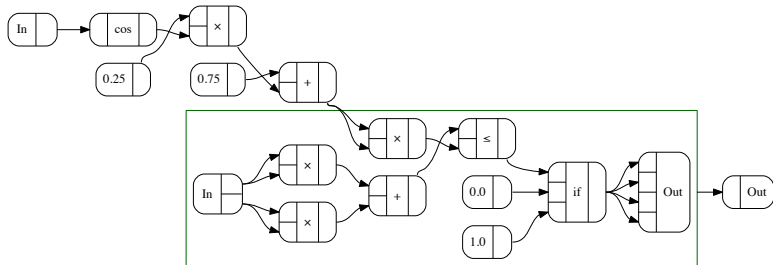
Example — graphics

$disk :: R \rightarrow Region$

$disk\ r\ p = magSqr\ p \leq sqr\ r$

$anim\ t = disk\ (3/4 + 1/4 * cos\ t)$

type $Region = R \times R \rightarrow Bool$



```
uniform float in0;
vec4 animA (float in1, float in2)
{ float v5 = 0.75 + 0.25 * cos (in0); // TODO: hoist
  float v24 = in1 * in1 + in2 * in2 <= v5 * v5 ? 0.0 : 1.0;
  return vec4 (v24, v24, v24, v24);
}
```

Differentiable functions

newtype $D\ a\ b = D\ (a \rightarrow (b \times (a \multimap b)))$ -- derivative as linear map

linearD $f = D\ (\lambda a \rightarrow (f\ a, \text{linear}\ f))$

instance *Category* D **where**

$id = \text{linearD}\ id$

$D\ g \circ D\ f = D\ (\lambda a \rightarrow \text{let } \{(b, f') = f\ a; (c, g') = g\ b\} \text{ in } (c, g' \circ f'))$

instance *Cartesian* D **where**

$exl = \text{linearD}\ exl$

$exr = \text{linearD}\ exr$

$D\ f \triangle D\ g = D\ (\lambda a \rightarrow \text{let } \{(b, f') = f\ a; (c, g') = g\ a\} \text{ in } ((b, c), f' \triangle g'))$

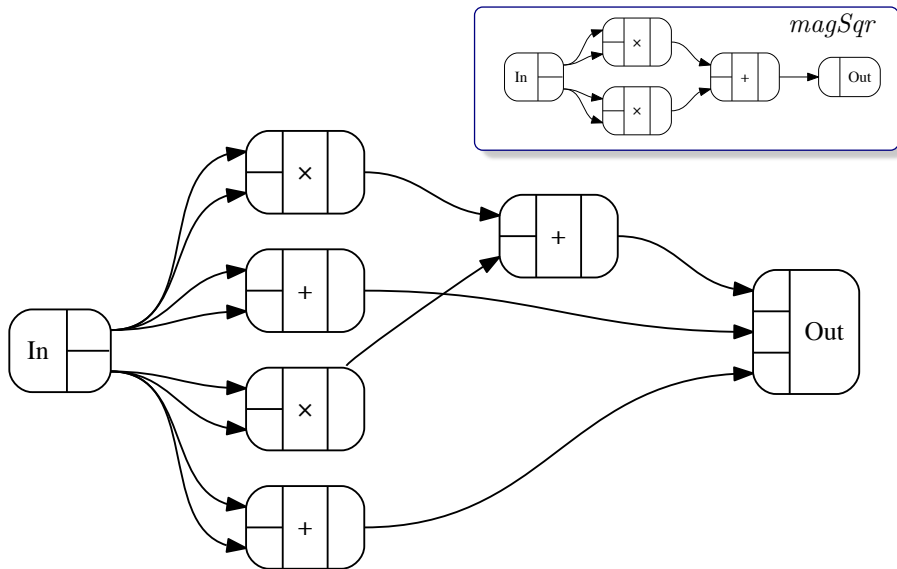
instance *NumCat* D **where**

$negateC = \text{linearD}\ negateC$

$addC = \text{linearD}\ addC$

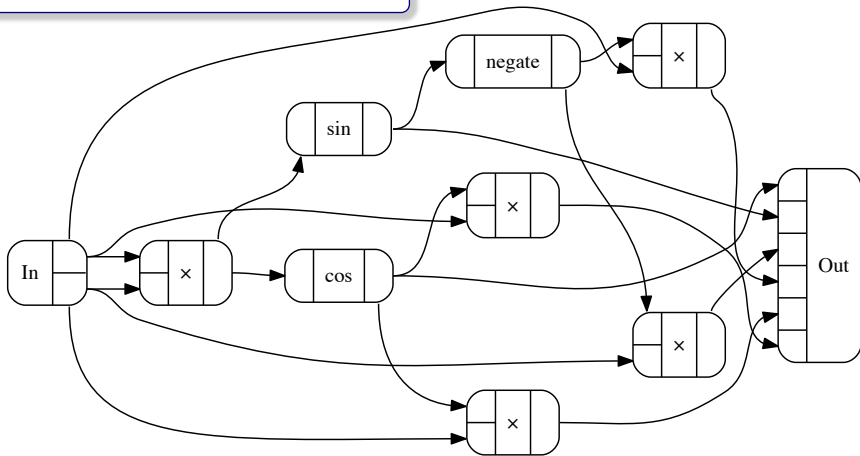
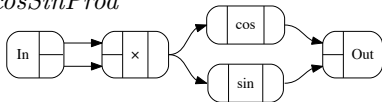
$mulC = D\ (mulC \triangle \lambda(a, b) \rightarrow \text{linear}\ (\lambda(da, db) \rightarrow da * b + db * a))$

Composing interpretations (*Graph* and *D*)



Composing interpretations (*Graph* and *D*)

cosSinProd



Interval analysis

data *IFun* $a\ b = \text{IFun } (\text{Interval } a \rightarrow \text{Interval } b)$

type family *Interval* a

type instance *Interval* *Double* = *Double* \times *Double*

type instance *Interval* $(a \times b) = \text{Interval } a \times \text{Interval } b$

type instance *Interval* $(a \rightarrow b) = \text{Interval } a \rightarrow \text{Interval } b$

instance *Category* *IFun* **where**

id = *IFun id*

IFun g \circ *IFun f* = *IFun (g* \circ *f)*

...

instance *Cartesian* *IFun* **where**

exl = *IFun exl*

exr = *IFun exr*

IFun f \triangle *IFun g* = *IFun (f* \triangle *g)*

instance $(\text{Interval } a \sim (a \times a), \text{Num } a, \text{Ord } a) \Rightarrow \text{NumCat } \text{IFun } a$ **where**

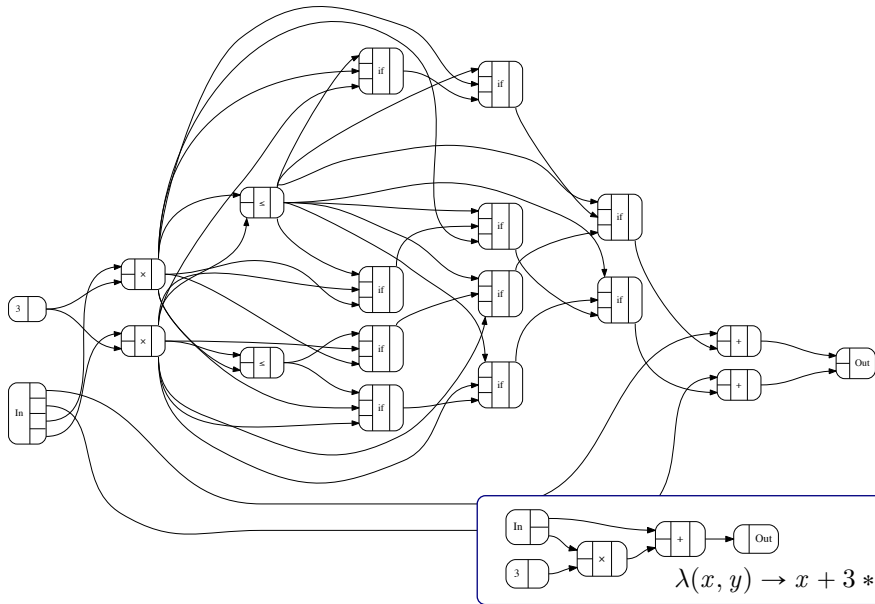
addC = *IFun* $(\lambda((a_{lo}, a_{hi}), (b_{lo}, b_{hi})) \rightarrow (a_{lo} + b_{lo}, a_{hi} + b_{hi}))$

mulC = *IFun* $(\lambda((a_{lo}, a_{hi}), (b_{lo}, b_{hi})) \rightarrow$

minmax $[a_{lo} * b_{lo}, a_{lo} * b_{hi}, a_{hi} * b_{lo}, a_{hi} * b_{hi}]$

...

Interval analysis — example



Other examples

- Constraint solving via SMT (with John Wiegley)
- Linear maps
- Incremental evaluation
- Polynomials
- Nondeterministic and probabilistic programming

Shallow embedding

- “Just a library”, but with a suitable host language.
- Easy to implement; but restricts optimization.
- Inherits host language & compiler *limitations*, e.g., no
 - differentiation or integration
 - incremental evaluation
 - optimization
 - constraint solving
 - novel back-ends, e.g., GPU, circuits, JavaScript

- Syntactic representation.
- More room for analysis and optimization.
- Harder to implement; redundant with host compiler.
- Requires some vocabulary changes.

Compiling to categories

- Just a library.
- Easy to implement.
- Analysis, optimization, non-standard target architectures.
- Non-standard operations on functions.