

# The essence and origins of FRP

*or*

How you could have invented  
Functional Reactive Programming

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# What is FRP?

## FRP's two fundamental properties

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- Precise, simple denotation. (Elegant & rigorous.)
- *Continuous* time. (Natural & composable.)

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Warning: most modern “FRP” systems have neither property. 😞

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FRP *is not* about:

- graphs,
- updates and propagation,
- streams,
- doing

# Why (precise & simple) denotation?

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## Why (precise & simple) denotation?

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- Separates specification from implementation.
- *Simple* so that we *can* reach conclusions.
- *Precise* so that our conclusions will be *true*.
- Denotations have elegant, functional-friendly style.

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An API is a language for communicating about a domain.

It helps to (really) understand what we're talking about.

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  - Fewer assumptions, more uses (resolution-independence).
  - More info available for extraction.
- Integration and differentiation: natural, accurate, efficient.

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- Integration and differentiation: natural, accurate, efficient.
- Quality/accuracy.
- Efficiency (adaptive).
- Reconcile differing input sampling rates.

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- Efficiency (adapative).
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*Principle: Approximations/prunings compose badly, so postpone.*

See *Why Functional Programming Matters*.

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Much of API and its specification can follow from this one choice.

# Original formulation

*time*        :: *Behavior T*  
*lift<sub>0</sub>*        :: *a → Behavior a*  
*lift<sub>1</sub>*        :: *(a → b) → Behavior a → Behavior b*  
*lift<sub>2</sub>*        :: *(a → b → c) → Behavior a → Behavior b → Behavior c*  
*timeTrans* :: *Behavior a → Behavior T → Behavior a*  
*integral*    :: *VS a ⇒ Behavior a → T → Behavior a*

...

**instance** *Num a ⇒ Num (Behavior a)* **where** ...

...

Reactivity later.

$$\begin{aligned}\mu \text{ time} &= \lambda t \rightarrow t \\ \mu (\text{lift}_0 a) &= \lambda t \rightarrow a \\ \mu (\text{lift}_1 f \text{ xs}) &= \lambda t \rightarrow f (\mu \text{ xs } t) \\ \mu (\text{lift}_2 f \text{ xs ys}) &= \lambda t \rightarrow f (\mu \text{ xs } t) (\mu \text{ ys } t) \\ \mu (\text{timeTrans } \text{xs } \text{tt}) &= \lambda t \rightarrow \mu \text{ xs } (\mu \text{ tt } t)\end{aligned}$$

**instance** *Num* *a*  $\Rightarrow$  *Num* (*Behavior* *a*) **where**

$$\text{fromInteger} = \text{lift}_0 \circ \text{fromInteger}$$

$$(+)$$
$$= \text{lift}_2 (+)$$

...

# Semantics

$$\begin{aligned}\mu \text{ time} &= \text{id} \\ \mu (\text{lift}_0 a) &= \text{const } a \\ \mu (\text{lift}_1 f \text{ } xs) &= f \circ \mu \text{ } xs \\ \mu (\text{lift}_2 f \text{ } xs \text{ } ys) &= \text{lift}_{A_2} f (\mu \text{ } xs) (\mu \text{ } ys) \\ \mu (\text{timeTrans } xs \text{ } tt) &= \mu \text{ } xs \circ \mu \text{ } tt\end{aligned}$$

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# Events

*Secondary type:*

$\mu :: \text{Event } a \rightarrow [(T, a)]$  -- non-decreasing times

$\text{never} :: \text{Event } a$

$\text{once} :: T \rightarrow a \rightarrow \text{Event } a$

$(\cdot | \cdot) :: \text{Event } a \rightarrow \text{Event } a \rightarrow \text{Event } a$

$(\implies) :: \text{Event } a \rightarrow (a \rightarrow b) \rightarrow \text{Event } b$

$\text{predicate} :: \text{Behavior Bool} \rightarrow \text{Event } ()$

$\text{snapshot} :: \text{Event } a \rightarrow \text{Behavior } b \rightarrow \text{Event } (a, b)$

*Exercise:* define semantics of these operations.

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Semantics:

$$\mu (b_0 \text{ 'switcher' } e) t = \mu (\text{last } (b_0 : \text{before } t (\mu e))) t$$

$$\text{before} :: T \rightarrow [(T, a)] \rightarrow [a]$$

$$\text{before } t \text{ os} = [a \mid (t_a, a) \leftarrow \text{os}, t_a < t]$$

Important:  $t_a < t$ , rather than  $t_a \leq t$ .

# A more elegant specification for FRP (teaser)

# API

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Replace operations with standard abstractions where possible:

**instance** *Functor Behavior* **where** ...

**instance** *Applicative Behavior* **where** ...

**instance** *Monoid a*  $\Rightarrow$  *Monoid (Behavior a)* **where** ...

**instance** *Functor Event* **where** ...

**instance** *Monoid (Event a)* **where** ...

Why?

# API

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**instance** *Functor Event* **where** ...

**instance** *Monoid (Event a)* **where** ...

Why?

- Less learning, more leverage.
- Specifications and laws for free.

## Specifications for free

The *instance's meaning* follows the *meaning's instance*:

$$\mu (fmap f as) \equiv fmap f (\mu as)$$

$$\mu (pure a) \equiv pure a$$

$$\mu (fs \langle * \rangle xs) \equiv \mu fs \langle * \rangle \mu xs$$

$$\mu \varepsilon \equiv \varepsilon$$

$$\mu (top \diamond bot) \equiv \mu top \diamond \mu bot$$

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- Corresponds exactly to the original FRP denotation.
- Follows inevitably from a domain-independent principle.
- Laws hold for free.

# History



- I went for graphics.
- Did program transformation, FP, type theory.
- Class in denotational semantics.

# 1989 at CMU

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- Kavi Arya's visit:
  - *Functional animation*
  - Streams of pictures
  - Elegant

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*Continuous time!*

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*Continuous time!*
- I finished my dissertation anyway.

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- 3D geometry etc as first-class immutable values.
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- Multi-way constraints on time-functions.  
Off-the-shelf constraint solvers (DeltaBlue & SkyBlue from UW).
- Differentiation, integration and ODEs specified via *derivative*.  
Adaptive Runge-Kutta-5 solver (fast & accurate).
- Reactivity via `assert/retract` (high-level but imperative).

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Adaptive Runge-Kutta-5 solver (fast & accurate).
- Reactivity via `assert/retract` (high-level but imperative).
- Optimizing compiler via partial evaluation.
- In Common Lisp, C++, Scheme.
- Efficient multi-user distributed execution for free.



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- TBAG + denotative/functional reactivity.
- Add event algebra to behavior algebra.
- Reactivity via behavior-valued events.
- Drop multi-way constraints “at first”.
- Started in ML as “RBML”.
- Rebranded to “ActiveVRML”, then “DirectAnimation”.

- Found Haskell: reborn as “RBMH” (research vehicle).
- Very fast implementation *via sprite engine*.
- John Hughes suggested using *Arrow*.

## 1999 at MSR: first try at push-based implementation

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- Algebra of imperative event listeners.
- Challenges:
  - Garbage collection & dependency reversal.
  - Determinacy of timing & simultaneity.
  - I doubt anyone has gotten correct.

## 2009: Push-pull FRP

- Minimal computation, low latency, *provably correct*.
- Push for reactivity and pull for continuous phases.
- “Push” is really blocked pull.
- More elegant API:
  - Standard abstractions.
  - Semantics as homomorphisms.
  - Laws for free.
- Reactive normal form, via equational properties (denotation!).
- Uses *lub* (basis of PL semantics).
- Implementation subtleties & GHC RTS bugs. Didn't quite work.

## 1996–2014: Paul Hudak / Yale

- Paul Hudak visited MSR in 1996 or so and saw RBMH.
- Encouraged publishing, and suggested collaboration.
- Proposed names “Fran” & “FRP”.
- *Many* FRP-based papers and theses.



July 15, 1952 – April 29, 2015

# Questions



“But computers are discrete, ...”