

Efficient automatic differentiation made easy
via elementary category theory

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What is differentiation? (Fréchet)

On Banach spaces a and b ,

$$\mathcal{D} :: (a \rightarrow b) \rightarrow (a \rightarrow (a \rightarrow b))$$

$f(a) + \mathcal{D}f(a)\varepsilon$ approximates $f(a + \varepsilon)$ for small ε .

$$\lim_{\varepsilon \rightarrow 0} \frac{\|f(a + \varepsilon) - (f(a) + \mathcal{D}f(a)\varepsilon)\|}{\|\varepsilon\|} = 0$$

See *Calculus on Manifolds* by Michael Spivak.

What is *automatic* differentiation?

Differentiation of computable functions is not computable.

Instead, differentiate *recipes*: $\llbracket \bar{\mathcal{D}} p \rrbracket = \mathcal{D} \llbracket p \rrbracket$.

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Differentiation composes messily in these forms

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Popular recipe forms: graphs, imperative programs, lambda calculus.

Differentiation composes messily in these forms,

but tidily in language of categories!

Composition

Sequential:

$$(\circ) :: (b \rightarrow c) \rightarrow (a \rightarrow b) \rightarrow (a \rightarrow c)$$

$$(g \circ f) a = g (f a)$$

$$\mathcal{D} (g \circ f) a = \mathcal{D} g (f a) \circ \mathcal{D} f a \quad \text{-- chain rule}$$

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Parallel:

$$\begin{aligned}(\triangle) &:: (a \rightarrow c) \rightarrow (a \rightarrow d) \rightarrow (a \rightarrow c \times d) \\(f \triangle g) a &= (f a, g a)\end{aligned}$$

$$\mathcal{D} (f \triangle g) a = \mathcal{D} f a \triangle \mathcal{D} g a$$

Linear functions

Linear functions

Linear functions are their own derivatives everywhere.

$$\mathcal{D} \text{ id } a = \text{id}$$

$$\mathcal{D} \text{ exl } a = \text{exl}$$

$$\mathcal{D} \text{ exr } a = \text{exr}$$

...

Chain rule:

$$\mathcal{D} (g \circ f) a = \mathcal{D} g (f a) \circ \mathcal{D} f a \quad \text{-- non-compositional}$$

Compositionality

Chain rule:

$$\mathcal{D} (g \circ f) a = \mathcal{D} g (f a) \circ \mathcal{D} f a \quad \text{-- non-compositional}$$

To fix, combine regular result with derivative:

$$\hat{\mathcal{D}} :: (a \rightarrow b) \rightarrow (a \rightarrow (b \times (a \multimap b)))$$

$$\hat{\mathcal{D}} f = f \triangle \mathcal{D} f \quad \text{-- specification}$$

so that $\mathcal{D} f = \text{err} \circ \hat{\mathcal{D}} f$.

Abstract algebra for functions

class *Category* (\rightsquigarrow) **where**

id :: $a \rightsquigarrow a$

(\circ) :: $(b \rightsquigarrow c) \rightarrow (a \rightsquigarrow b) \rightarrow (a \rightsquigarrow c)$

class *Category* (\rightsquigarrow) \Rightarrow *Cartesian* (\rightsquigarrow) **where**

exl :: $(a \times b) \rightsquigarrow a$

exr :: $(a \times b) \rightsquigarrow b$

(Δ) :: $(a \rightsquigarrow c) \rightarrow (a \rightsquigarrow d) \rightarrow (a \rightsquigarrow (c \times d))$

Plus laws and classes for arithmetic etc.

Automatic differentiation (specification)

newtype $D\ a\ b = D\ (a \rightarrow b \times (a \rightarrow b))$

$\hat{\mathcal{D}} :: (a \rightarrow b) \rightarrow D\ a\ b$

$\hat{\mathcal{D}}\ f = D\ (f \triangle \mathcal{D}\ f)$ -- not computable

Automatic differentiation (specification)

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$\hat{D} :: (a \rightarrow b) \rightarrow D\ a\ b$

$\hat{D}\ f = D\ (f \triangle \mathcal{D}\ f)$ -- not computable

Specification: \hat{D} is a cartesian functor, i.e.,

$$\hat{D}\ id = id$$

$$\hat{D}\ (g \circ f) = \hat{D}\ g \circ \hat{D}\ f$$

$$\hat{D}\ exl = exl$$

$$\hat{D}\ exr = exr$$

$$\hat{D}\ (f \triangle g) = \hat{D}\ f \triangle \hat{D}\ g$$

The game: solve these equations for the RHS operations.

Automatic differentiation (solution)

newtype $D\ a\ b = D\ (a \rightarrow b \times (a \multimap b))$

linearD $f = D\ (\lambda a \rightarrow (f\ a, f))$

instance *Category* D **where**

$id = linearD\ id$

$D\ g \circ D\ f = D\ (\lambda a \rightarrow \mathbf{let}\ \{(b, f') = f\ a; (c, g') = g\ b\}\ \mathbf{in}\ (c, g' \circ f'))$

instance *Cartesian* D **where**

$exl = linearD\ exl$

$exr = linearD\ exr$

$D\ f \triangle D\ g = D\ (\lambda a \rightarrow \mathbf{let}\ \{(b, f') = f\ a; (c, g') = g\ a\}\ \mathbf{in}\ ((b, c), f' \triangle g'))$

instance *NumCat* D **where**

$negateC = linearD\ negateC$

$addC = linearD\ addC$

$mulC = D\ (mulC \triangle (\lambda(a, b) \rightarrow \lambda(da, db) \rightarrow b * da + a * db))$

Generalizing AD

newtype $D\ a\ b = D\ (a \rightarrow b \times (a \multimap b))$

linearD $f = D\ (\lambda a \rightarrow (f\ a, f))$

instance *Category* D **where**

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instance *Cartesian* D **where**

$exl = linearD\ exl$

$exr = linearD\ exr$

$D\ f \triangle D\ g = D\ (\lambda a \rightarrow \mathbf{let}\ \{(b, f') = f\ a; (c, g') = g\ a\}\ \mathbf{in}\ ((b, c), f' \triangle g'))$

Each D operation just uses corresponding (\multimap) operation.

Generalize from (\multimap) to other cartesian categories.

Generalized AD

newtype $D_{(\rightsquigarrow)}$ $a \rightarrow b = D (a \rightarrow b \times (a \rightsquigarrow b))$

linearD $f f' = D (\lambda a \rightarrow (f a, f'))$

instance *Category* $(\rightsquigarrow) \Rightarrow$ *Category* $D_{(\rightsquigarrow)}$ **where**

$id = \text{linearD } id \ id$

$D \ g \circ D \ f = D (\lambda a \rightarrow \mathbf{let} \ \{(b, f') = f \ a; (c, g') = g \ b\} \ \mathbf{in} \ (c, g' \circ f'))$

instance *Cartesian* $(\rightsquigarrow) \Rightarrow$ *Cartesian* $D_{(\rightsquigarrow)}$ **where**

$exl = \text{linearD } exl \ exl$

$exr = \text{linearD } exr \ exr$

$D \ f \ \Delta \ D \ g = D (\lambda a \rightarrow \mathbf{let} \ \{(b, f') = f \ a; (c, g') = g \ a\} \ \mathbf{in} \ ((b, c), f' \ \Delta \ g'))$

instance $\dots \Rightarrow$ *NumCat* D **where**

$negateC = \text{linearD } negateC \ negateC$

$addC = \text{linearD } addC \ addC$

$mulC = ??$

Numeric operations

Specific to (linear) *functions*:

$$\mathit{mulC} = D (\mathit{mulC} \triangle (\lambda(a, b) \rightarrow \lambda(da, db) \rightarrow b * da + a * db))$$

Numeric operations

Specific to (linear) *functions*:

$$\text{mul}C = D (\text{mul}C \triangle (\lambda(a, b) \rightarrow \lambda(da, db) \rightarrow b * da + a * db))$$

Rephrase:

$$\text{scale} :: \text{Multiplicative } a \Rightarrow a \rightarrow (a \rightarrow a)$$

$$\text{scale } u = \lambda v \rightarrow u * v$$

$$(\nabla) :: \text{Additive } c \Rightarrow (a \rightarrow c) \rightarrow (b \rightarrow c) \rightarrow ((a \times b) \rightarrow c)$$

$$(f \nabla g) (a, b) = f a + g b$$

Now

$$\text{mul}C = D (\text{mul}C \triangle (\lambda(a, b) \rightarrow \text{scale } b \nabla \text{scale } a))$$

New generalized vocabulary

class *Category* (\rightsquigarrow) \Rightarrow *Cocartesian* _{\times} (\rightsquigarrow) **where**

inl :: $a \rightsquigarrow (a \times b)$

inr :: $b \rightsquigarrow (a \times b)$

(∇) :: $(a \rightsquigarrow c) \rightarrow (b \rightsquigarrow c) \rightarrow ((a \times b) \rightsquigarrow c)$

class *ScalarCat* (\rightsquigarrow) **where**

scale :: $a \rightarrow (a \rightsquigarrow a)$

Differentiation:

$$\mathcal{D} (f \nabla g) (a, b) = \mathcal{D} f a \nabla \mathcal{D} g b$$

The rest are linear.

Linear maps as functions

newtype $a \rightarrow b = LFun (a \rightarrow b)$ -- *linear*

instance *Category* (\rightarrow) **where**

$id = LFun id$

$(\circ) = inNew_2 (\circ)$

instance *Cartesian* (\rightarrow) **where**

$exl = LFun exl$

$exr = LFun exr$

$(\Delta) = inNew_2 (\Delta)$

instance *Cocartesian* _{\times} (\rightarrow) **where**

$inl = LFun (\lambda a \rightarrow (a, 0))$

$inr = LFun (\lambda b \rightarrow (0, b))$

$(\nabla) = inNew_2 (\lambda f g (a, b) \rightarrow f a + g b)$

instance *Multiplicative* $s \Rightarrow ScalarCat (\rightarrow) s$ **where**

$scale s = LFun (s *)$

Extracting a data representation

- Finally, extract a matrix or gradient vector.
- Very inefficient for gradient-based optimization!
- Alternatively, represent as “generalized matrices” (M_s a b). Then solve more homomorphisms.

Efficiency of composition

- Composition is associative.
- Some associations are more efficient than others, so
 - Associate optimally.
 - Equivalent to *matrix chain multiplication* — $O(n \log n)$.
 - Choice determined by *types*, i.e., compile-time information.

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- Composition is associative.
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 - Associate optimally.
 - Equivalent to *matrix chain multiplication* — $O(n \log n)$.
 - Choice determined by *types*, i.e., compile-time information.
- All right: “forward mode AD” (FAD).
- All left: “reverse mode AD” (RAD).
- RAD is *much* better for gradient-based optimization.

Left-associating composition (RAD)

CPS-like category:

- Represent $a \rightsquigarrow b$ by $(b \rightsquigarrow r) \rightarrow (a \rightsquigarrow r)$.
- Meaning: $f' \mapsto (\lambda h \rightarrow h \circ f')$.
- Construct $h \circ \mathcal{D} f a$ directly, without $\mathcal{D} f a$.

Old technique (Cayley 1854), vastly generalized by Yoneda.

Continuation category (specification)

newtype $ContC (\rightsquigarrow) r a b = Cont ((b \rightsquigarrow r) \rightarrow (a \rightsquigarrow r))$

$cont :: Category (\rightsquigarrow) \Rightarrow (a \rightsquigarrow b) \rightarrow ContC (\rightsquigarrow) r a b$
 $cont f = Cont (\circ f)$

Specification: $cont$ is a cartesian functor.

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Specification: $cont$ is a cartesian functor.

We'll use an isomorphism:

$join :: Cocartesian (\rightsquigarrow) \Rightarrow (c \rightsquigarrow a) \times (d \rightsquigarrow a) \rightarrow ((c \times d) \rightsquigarrow a)$

$unjoin :: Cocartesian (\rightsquigarrow) \Rightarrow ((c \times d) \rightsquigarrow a) \rightarrow (c \rightsquigarrow a) \times (d \rightsquigarrow a)$

$join (f, g) = f \nabla g$

$unjoin h = (h \circ inl, h \circ inr)$

Continuation category (solution)

instance $Category (\sim\rightarrow) \Rightarrow Category (ContC (\sim\rightarrow) r)$ **where**

$id = Cont\ id$

$Cont\ g \circ Cont\ f = Cont\ (f \circ g)$

instance $Cartesian (\sim\rightarrow) \Rightarrow Cartesian (ContC (\sim\rightarrow) r)$ **where**

$exl = Cont\ (join \circ inl)$

$exr = Cont\ (join \circ inr)$

$(\Delta) = inNew_2 (\lambda f\ g \rightarrow (f \nabla g) \circ unjoin)$

instance $Cocartesian_x (\sim\rightarrow) \Rightarrow Cocartesian_x (ContC (\sim\rightarrow) r)$ **where**

$inl = Cont\ (exl \circ unjoin)$

$inr = Cont\ (exr \circ unjoin)$

$(\nabla) = inNew_2 (\lambda f\ g \rightarrow join \circ (f \Delta g))$

instance $ScalarCat (\sim\rightarrow) a \Rightarrow ScalarCat (ContC (\sim\rightarrow) r) a$ **where**

$scale\ s = Cont\ (scale\ s)$

Reverse-mode AD without tears

$$D_{ContC} M_s r$$

- Vector space dual: $u^* = u \multimap s$, with u a vector space over s .
- If u has finite dimension, then $u^* \cong u$.
- Represent $a \multimap b$ by $b^* \rightarrow a^*$ by $b \rightarrow a$.
- *Ideal* for extracting gradient vector. Just apply to 1 (*id*).

Duality (specification)

newtype $Dual_{(\rightsquigarrow)}$ $a\ b = Dual\ (b \rightsquigarrow a)$

$asDual :: ContC\ (\rightsquigarrow)\ s\ a\ b \rightarrow Dual_{(\rightsquigarrow)}\ a\ b$

$asDual\ (Cont\ f) = Dual\ (dot^{-1} \circ f \circ dot)$

where

$dot :: u \rightarrow (u \multimap s)$

$dot^{-1} :: (u \multimap s) \rightarrow u$

Specification: $asDual$ is a cartesian functor.

Duality (solution)

newtype $Dual_{(\rightsquigarrow)}$ $a\ b = Dual\ (b \rightsquigarrow a)$

instance $Category\ (\rightsquigarrow) \Rightarrow Category\ Dual_{(\rightsquigarrow)}$ **where**

$id = Dual\ id$

$(\circ) = inNew_2\ (flip\ (\circ))$

instance $Cocartesian_{\times}\ (\rightsquigarrow) \Rightarrow Cartesian\ Dual_{(\rightsquigarrow)}$ **where**

$exl = Dual\ inl$

$exr = Dual\ inr$

$(\Delta) = inNew_2\ (\nabla)$

instance $Cartesian\ (\rightsquigarrow) \Rightarrow Cocartesian_{\times}\ Dual_{(\rightsquigarrow)}$ **where**

$inl = Dual\ exl$

$inr = Dual\ exr$

$(\nabla) = inNew_2\ (\Delta)$

instance $ScalarCat\ (\rightsquigarrow)\ s \Rightarrow ScalarCat\ Dual_{(\rightsquigarrow)}\ s$ **where**

$scale\ s = Dual\ (scale\ s)$

Backpropagation

Backpropagation

$D_{Dual \rightarrow}$

Conclusions

- Simple AD algorithm, specializing to forward, reverse, mixed.
- No graphs, tapes, tags, partial derivatives, or mutation.
- Parallel-friendly and possibly low memory use.
- Calculated from simple, regular algebra problems.
- Generalizes to derivative categories other than linear maps.
- Differentiate regular Haskell code (via plugin).
- [ICFP 2018 paper](#): pictures, proofs, incremental computation.

Running examples

$sqr :: Num\ a \Rightarrow a \rightarrow a$

$sqr\ a = a * a$

$magSqr :: Num\ a \Rightarrow a \times a \rightarrow a$

$magSqr\ (a, b) = sqr\ a + sqr\ b$

$cosSinProd :: Floating\ a \Rightarrow a \times a \rightarrow a \times a$

$cosSinProd\ (x, y) = (\cos\ z, \sin\ z)$ **where** $z = x * y$

Running examples

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In categorical vocabulary:

$sqr = mulC \circ (id \triangle id)$

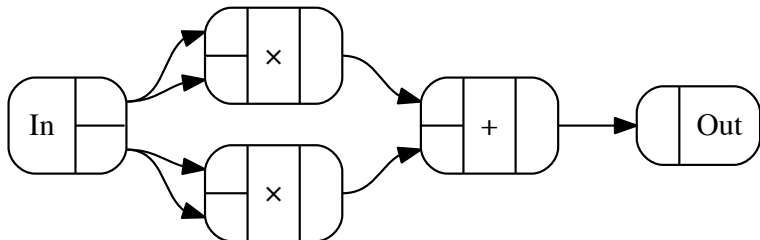
$magSqr = addC \circ ((sqr \circ exl) \triangle (sqr \circ exr))$

$cosSinProd = (cosC \triangle sinC) \circ mulC$

Visualizing computations

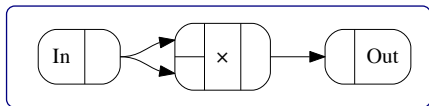
$$\text{magSqr } (a, b) = \text{sqr } a + \text{sqr } b$$

$$\text{magSqr} = \text{addC} \circ ((\text{sqr} \circ \text{exl}) \triangle (\text{sqr} \circ \text{exr}))$$



Auto-generated from Haskell code. See *Compiling to categories*.

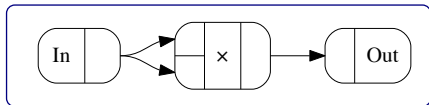
AD example



$$\text{sqr } a = a * a$$

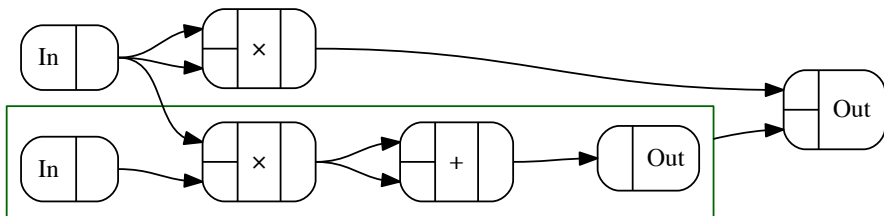
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AD example



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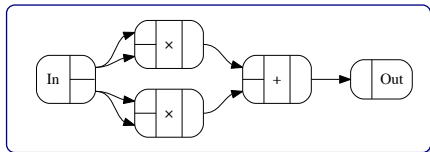
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AD example

$$\text{magSqr}(a, b) = \text{sqr } a + \text{sqr } b$$

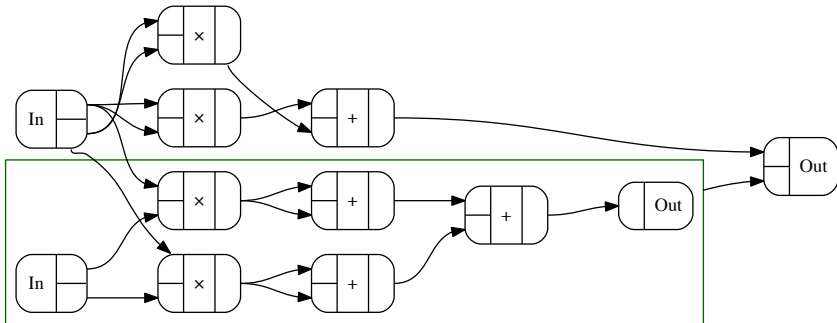
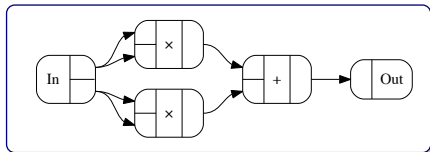
$$\text{magSqr} = \text{addC} \circ ((\text{sqr} \circ \text{exl}) \Delta (\text{sqr} \circ \text{exr}))$$



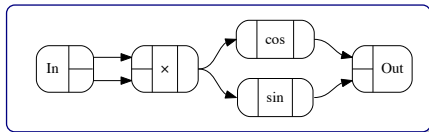
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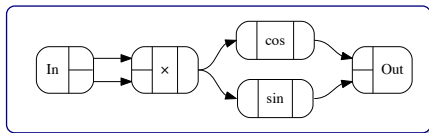
AD example



$\text{cosSinProd}(x, y) = (\cos z, \sin z)$ **where** $z = x * y$

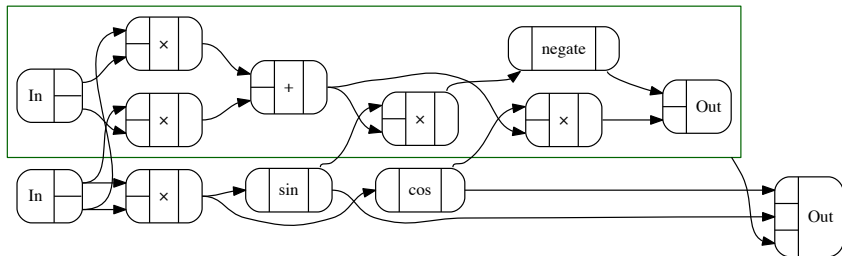
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AD example

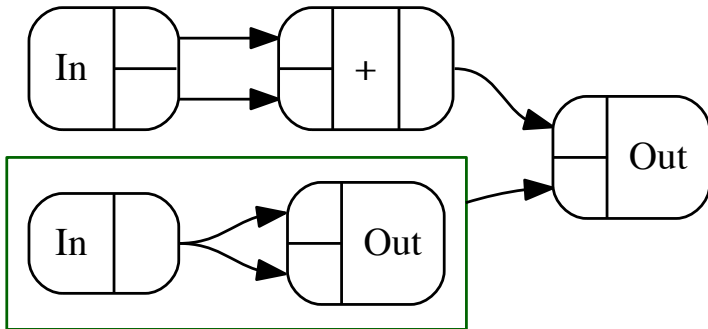
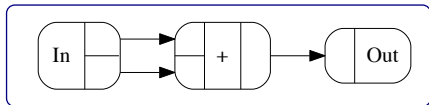


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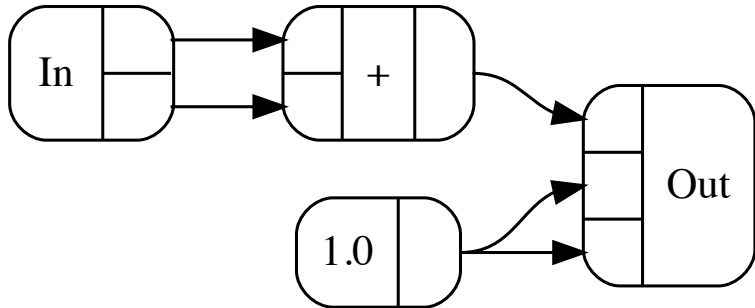
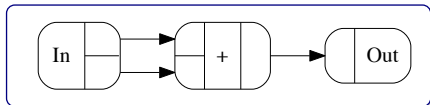
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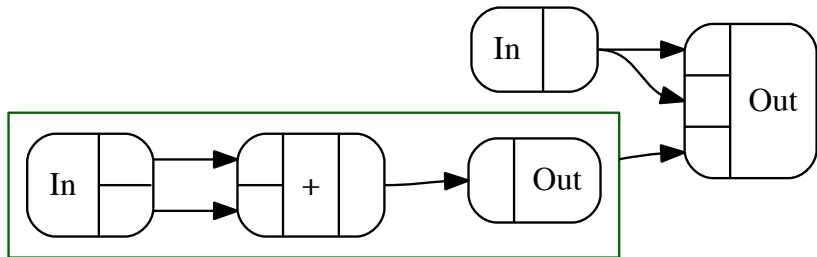
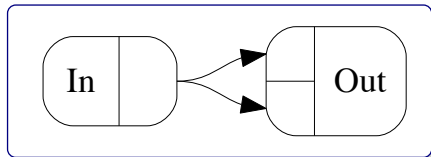
RAD example (dual function)



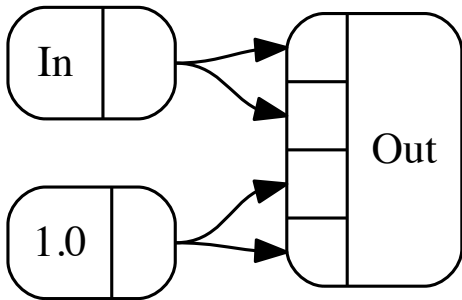
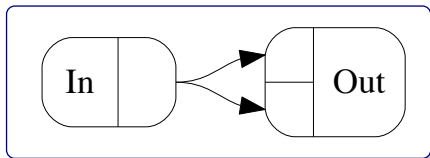
RAD example (dual vector)



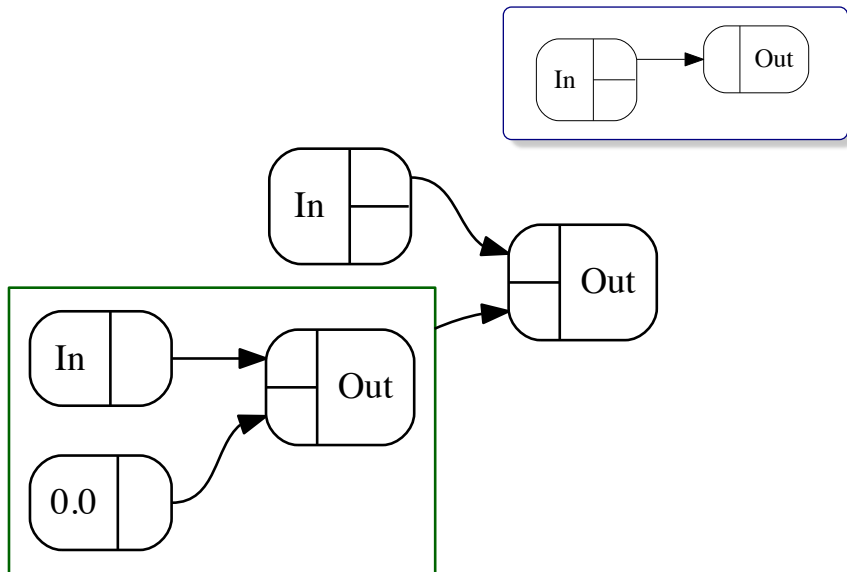
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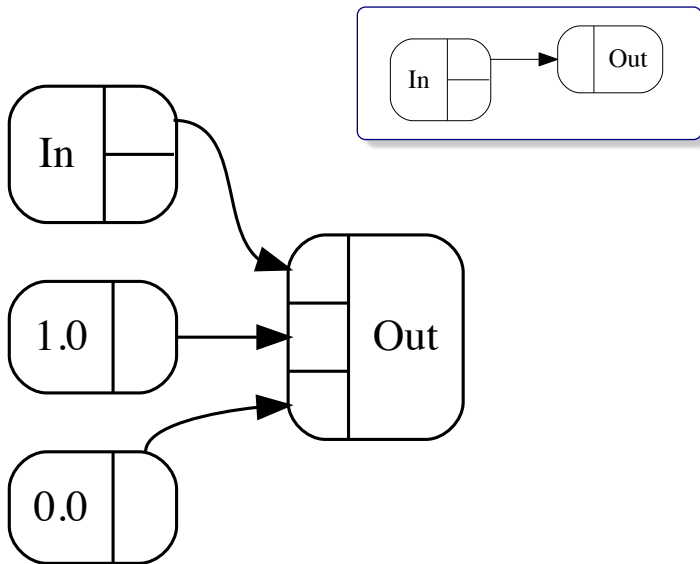
RAD example (vector)



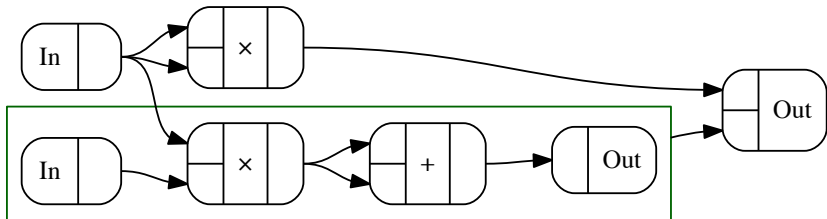
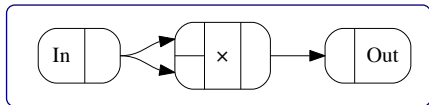
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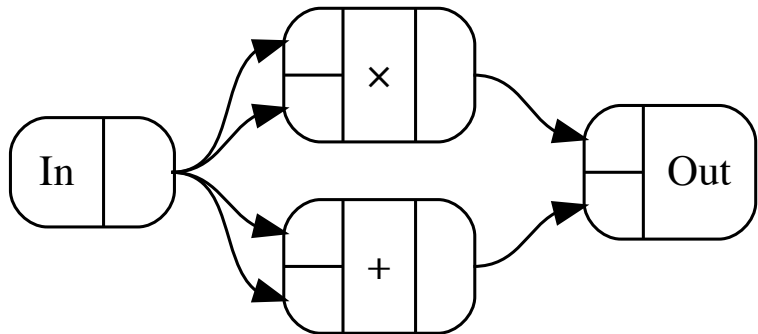
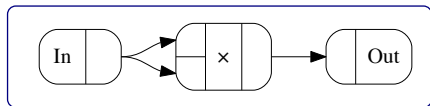
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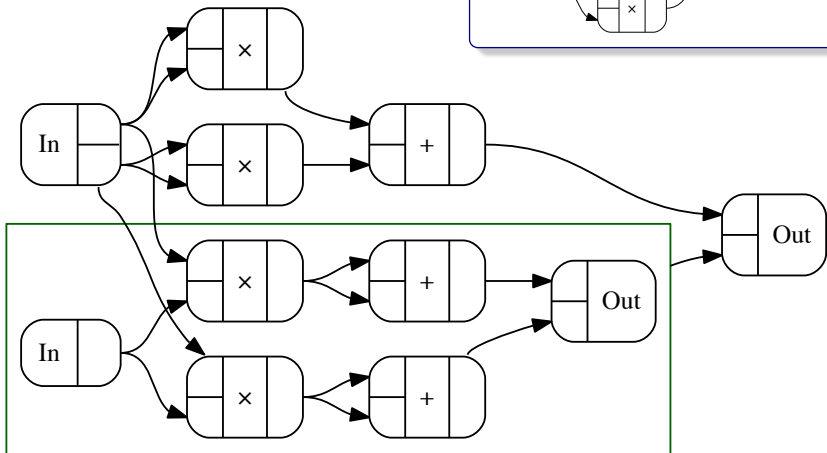
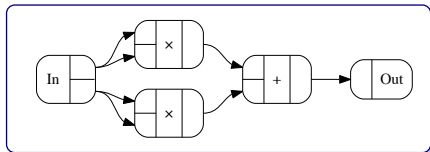
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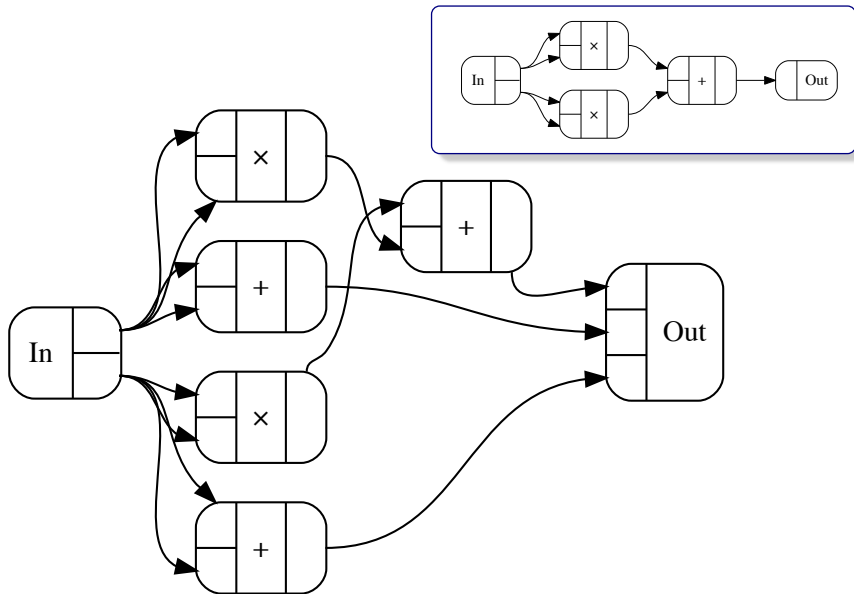
RAD example (dual vector)



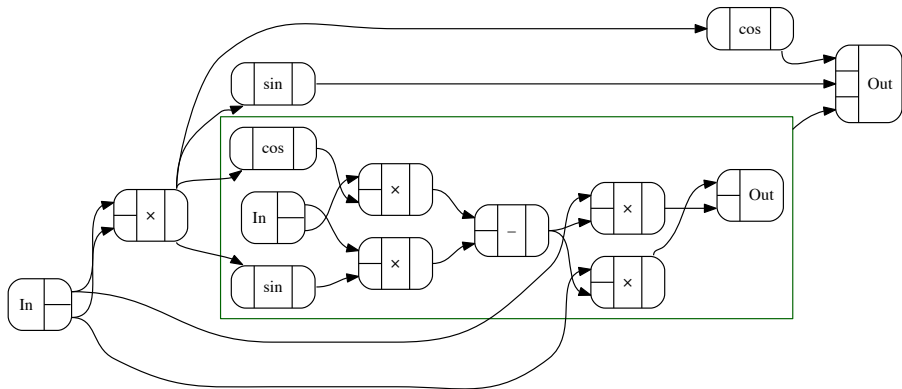
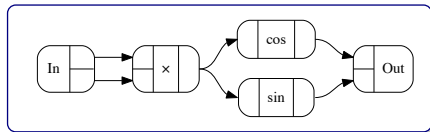
RAD example (dual function)



RAD example (dual vector)



RAD example (dual function)



Reflections: recipe for success

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Solution: Compiling to categories.

Symbolic vs automatic differentiation

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- *Symbolic*:
 - Apply differentiation rules symbolically.
 - Can duplicate much work.
 - Needs algebraic manipulation.
- *Automatic*:
 - FAD: easy to implement but often inefficient.
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My view: *AD is SD done by a compiler.*

Compilers already work symbolically and preserve sharing.