

Teaching new tricks to old programs

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Target Data Sciences

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New vocabularies, not new languages.



The Next 700 Programming Languages

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“... today ... 1,700 special programming languages used to ‘communicate’ in over 700 application areas.”—*Computer Software Issues*, an American Mathematical Association Prospectus, July 1965.

Can we create fewer new vocabularies as well?

What does it mean?

$$x + 3 * y$$

It depends on x and y .

What does it mean?

$$\lambda x y \rightarrow x + 3 * y$$

It depends on $+$, $*$, and 3 .

What does it mean?

$$\lambda x y \rightarrow x + 3 * y$$

It depends on $+$, $*$, and 3 :

- *Int, Float, Double*
- $\mathbb{Z}, \mathbb{N}, \mathbb{Q}, \mathbb{R}, \mathbb{C}$
- Vectors
- Polynomials
- Functions
- Regular expressions/languages
- Arbitrary rings, semirings,

Organizing interpretations

- Abstract algebra: interfaces and laws, e.g.,
 - Monoid, group, ring
 - Vector space
 - Functor, applicative, monad, foldable, traversable
 - Category, with products, with coproducts/sums
- Refactor and repurpose proofs and programs. (More with less.)

Example,

$$\text{fold} :: (\text{Foldable } f, \text{Monoid } m) \Rightarrow f\ m \rightarrow m$$

What does it mean?

$$\lambda x y \rightarrow x + 3 * y$$

- The most basic “operations”: λ , variables, and application.
- We can't re-interpret/overload.
- What if there were a way?

Why overload lambda (etc)?

Same benefits as algebraic abstraction:

- Convenient notation.
- Generalized, principled interpretation.
- Modular programming and reasoning.

Why overload lambda?

- Convenient notation for functions.
- Alternative function implementations:
 - GPU code
 - Circuits
 - Javascript
- Enhanced functions:
 - Derivatives and integrals
 - Incremental evaluation
 - Interval analysis
 - Optimization
 - Root-finding
 - Constraint solving

How to overload lambda?

- Idea: eliminate it, and overload as usual.
- How?

Eliminating lambda

Introducing lambda

$const :: b \rightarrow (a \rightarrow b)$

$const\ b = \lambda a \rightarrow b$

$id :: a \rightarrow a$

$id = \lambda a \rightarrow a$

$(\circ) :: (b \rightarrow c) \rightarrow (a \rightarrow b) \rightarrow (a \rightarrow c)$

$g \circ f = \lambda a \rightarrow g (f\ a)$

$(\Delta) :: (a \rightarrow c) \rightarrow (a \rightarrow d) \rightarrow (a \rightarrow c \times d)$

$f \Delta g = \lambda a \rightarrow (f\ a, g\ a)$

$curry :: (a \times b \rightarrow c) \rightarrow (a \rightarrow b \rightarrow c)$

$curry\ f = \lambda a \rightarrow \lambda b \rightarrow f\ (a, b)$

$apply :: (a \rightarrow b) \times a \rightarrow b$

$apply = \lambda(f, a) \rightarrow f\ a$

$= uncurry\ id$

Eliminating lambda

Systematically *un-inline*:

$$(\lambda p \rightarrow k) \quad \dashrightarrow \text{const } k$$

$$(\lambda p \rightarrow p) \quad \dashrightarrow \text{id}$$

$$(\lambda p \rightarrow u \ v) \quad \dashrightarrow \text{apply} \circ ((\lambda p \rightarrow u) \triangle (\lambda p \rightarrow v))$$

$$\begin{aligned} (\lambda p \rightarrow \lambda q \rightarrow u) &\dashrightarrow \text{curry } (\lambda(p, q) \rightarrow u) \\ &\dashrightarrow \text{curry } (\lambda r \rightarrow u [p := \text{fst } r, q := \text{snd } r]) \end{aligned}$$

Automate via a compiler plugin.

Examples

$sqr :: Num\ a \Rightarrow a \rightarrow a$

$sqr\ a = a * a$

$magSqr :: Num\ a \Rightarrow a \times a \rightarrow a$

$magSqr\ (a, b) = sqr\ a + sqr\ b$

$cosSinProd :: Floating\ a \Rightarrow a \times a \rightarrow a \times a$

$cosSinProd\ (x, y) = (cos\ z, sin\ z)$ **where** $z = x * y$

After λ -elimination:

$sqr = mulC \circ (id \triangle id)$

$magSqr = addC \circ (mulC \circ (exl \triangle exl) \triangle mulC \circ (exr \triangle exr))$

$cosSinProd = (cosC \triangle sinC) \circ mulC$

Abstract algebra for functions

Interface:

class *Category* *k* **where**

id :: *a* `k` *a*

(◦) :: (*b* `k` *c*) → (*a* `k` *b*) → (*a* `k` *c*)

infixr 9 ◦

Laws:

$$id \circ f \equiv f$$

$$g \circ id \equiv g$$

$$(h \circ g) \circ f \equiv h \circ (g \circ f)$$

Products

Interface:

```
class Category k  $\Rightarrow$  Cartesian k where  
  type  $a \times_k b$   
  exl ::  $(a \times_k b) \rightarrow k \rightarrow a$   
  exr ::  $(a \times_k b) \rightarrow k \rightarrow b$   
   $(\Delta)$  ::  $(a \rightarrow k \rightarrow c) \rightarrow (a \rightarrow k \rightarrow d) \rightarrow (a \rightarrow k \rightarrow (c \times_k d))$   
  infixr 3  $\Delta$ 
```

Laws:

$$\begin{aligned} \text{exl} \circ (f \Delta g) &\equiv f \\ \text{exr} \circ (f \Delta g) &\equiv g \\ \text{exl} \circ h \Delta \text{exr} \circ h &\equiv h \end{aligned}$$

Coproducts

Dual to product.

```
class Category  $k \Rightarrow \text{Cocartesian } k$  where  
  type  $a +_k b$   
   $inl :: a \backslash k \backslash (a +_k b)$   
   $inr :: b \backslash k \backslash (a +_k b)$   
   $(\nabla) :: (a \backslash k \backslash c) \rightarrow (b \backslash k \backslash c) \rightarrow ((a +_k b) \backslash k \backslash c)$   
  infixr 2  $\nabla$ 
```

Laws:

$$(f \nabla g) \circ inl \quad \equiv f$$
$$(f \nabla g) \circ inr \quad \equiv g$$
$$h \circ inl \nabla h \circ inr \equiv h$$

Exponentials

First-class “functions” (morphisms):

```
class Cartesian  $k \Rightarrow$  Closed  $k$  where  
  type  $a \Rightarrow_k b$   
  apply    :: (( $a \Rightarrow_k b$ )  $\times_k a$ ) `k`  $b$   
  curry    :: (( $a \times_k b$ ) `k`  $c$ )  $\rightarrow$  ( $a$  `k` ( $b \Rightarrow_k c$ ))  
  uncurry  :: ( $a$  `k` ( $b \Rightarrow_k c$ ))  $\rightarrow$  (( $a \times_k b$ ) `k`  $c$ )
```

Laws:

$$\begin{aligned} \text{uncurry } (\text{curry } f) &\equiv f \\ \text{curry } (\text{uncurry } g) &\equiv g \\ \text{apply} \circ (\text{curry } f \circ \text{exl} \triangle \text{exr}) &\equiv f \end{aligned}$$

Misc operations

```
class NumCat k a where  
  negateC      :: a `k` a  
  addC, sub, mulC :: (a ×k a) `k` a  
  ...  
  ...
```

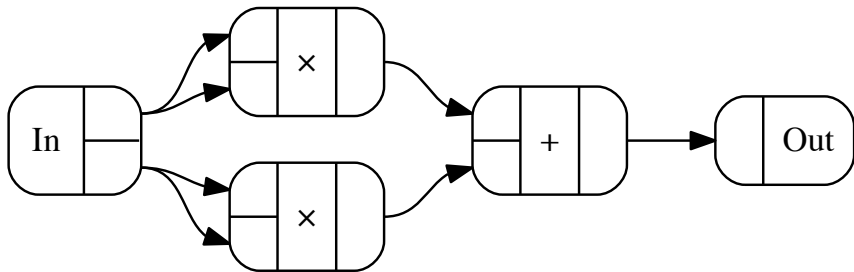
Changing interpretations

- We've eliminated lambdas and variables
- and replaced them with an algebraic vocabulary.
- What happens if we *replace* (\rightarrow) *with other instances*?
(Via compiler plugin.)

Computation graphs — example

$$\text{magSqr}(a, b) = \text{sqr } a + \text{sqr } b$$

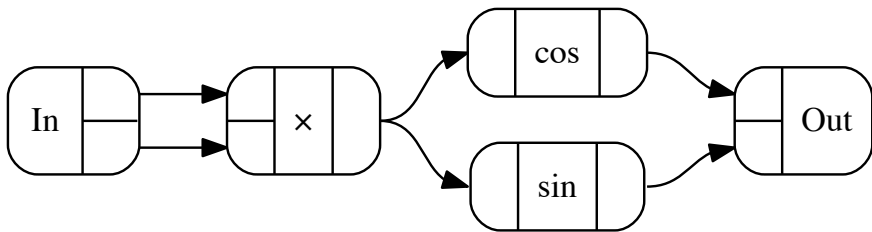
$$\text{magSqr} = \text{addC} \circ (\text{mulC} \circ (\text{exl} \triangle \text{exl}) \triangle \text{mulC} \circ (\text{exr} \triangle \text{exr}))$$



Computation graphs — example

$\text{cosSinProd}(x, y) = (\text{cos } z, \text{sin } z)$ **where** $z = x * y$

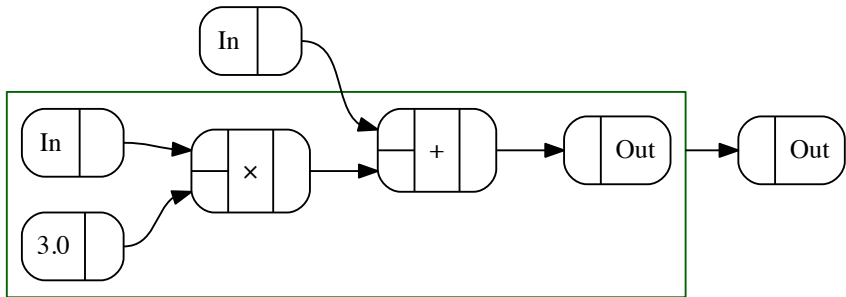
$\text{cosSinProd} = (\text{cosC} \Delta \text{sinC}) \circ \text{mulC}$



Computation graphs — example

$\lambda x y \rightarrow x + 3 * y$

$\text{curry} (\text{addC} \circ (\text{exl} \triangle \text{mulC} \circ (\text{const } 3.0 \triangle \text{exr})))$



Computation graphs — implementation sketch

newtype *Graph* *a b* = *Graph* (*Ports a* → *GraphM* (*Ports b*))

type *GraphM* = *State* (*PortNum*, [*Comp*])

data *Comp* = $\forall a b. \text{Comp } (\text{Template } a b) (\text{Ports } a) (\text{Ports } b)$

data *Template* :: * → * → * **where**

Prim :: *String* → *Template a b*

Subgraph :: *Graph a b* → *Template () (a → b)*

instance *Category Graph* **where**

id = *Graph return*

Graph g ∘ *Graph f* = *Graph (g <=< f)*

instance *BoolCat Graph* **where**

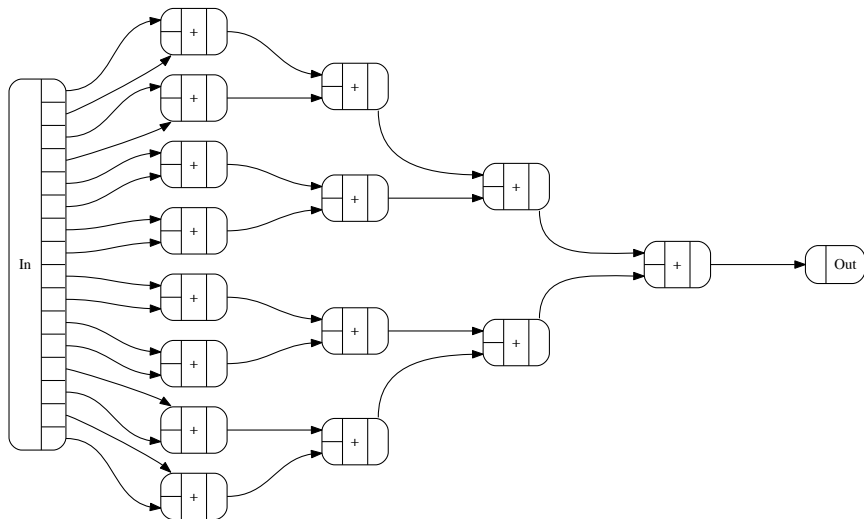
notC = *genComp* "¬"

andC = *genComp* "∧"

orC = *genComp* "∨"

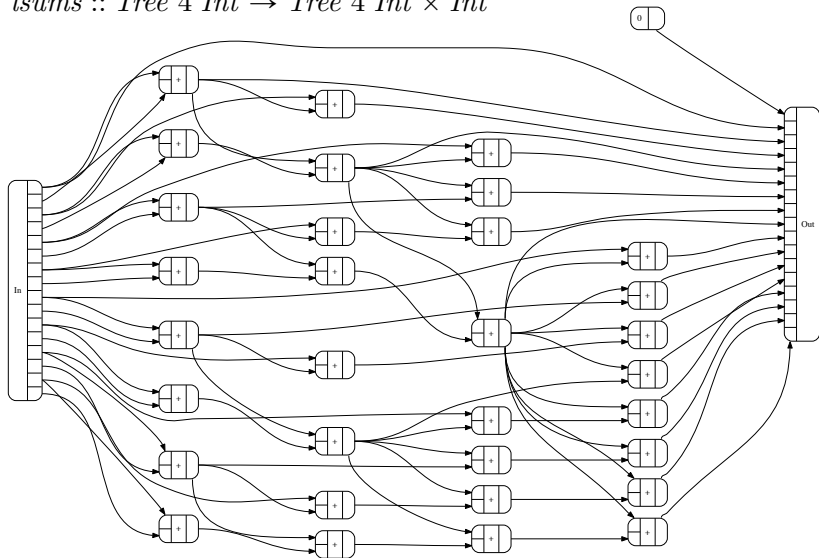
Computation graphs — fold

sum :: Tree 4 Int → Int



Computation graphs — scan

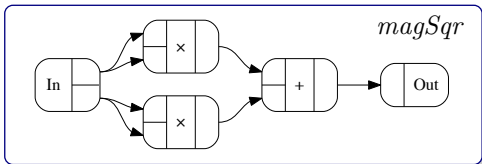
lsums :: Tree 4 Int \rightarrow Tree 4 Int \times Int



Haskell to hardware

Convert graphs to Verilog:

```
module magSqr (In_0, In_1, Out);  
  input [31:0] In_0;  
  input [31:0] In_1;  
  output [31:0] Out;  
  wire [31:0] Plus_I0;  
  wire [31:0] Times_I3;  
  wire [31:0] Times_I4;  
  assign Plus_I0 = Times_I3 + Times_I4;  
  assign Out = Plus_I0;  
  assign Times_I3 = In_0 * In_0;  
  assign Times_I4 = In_1 * In_1;  
endmodule
```



Automatic differentiation

data $D\ a\ b = D\ (a \rightarrow b \times (a \multimap b))$ -- Derivatives are linear maps.

linearD $f = D\ (\lambda a \rightarrow (f\ a, \text{linear}\ f))$

instance *Category* D **where**

$id = \text{linearD}\ id$

$D\ g \circ D\ f = D\ (\lambda a \rightarrow \mathbf{let}\ \{(b, f') = f\ a; (c, g') = g\ b\}\ \mathbf{in}\ (c, g' \circ f'))$

instance *Cartesian* D **where**

$exl = \text{linearD}\ exl$

$exr = \text{linearD}\ exr$

$D\ f \triangle D\ g = D\ (\lambda a \rightarrow \mathbf{let}\ \{(b, f') = f\ a; (c, g') = g\ a\}\ \mathbf{in}\ ((b, c), f' \triangle g'))$

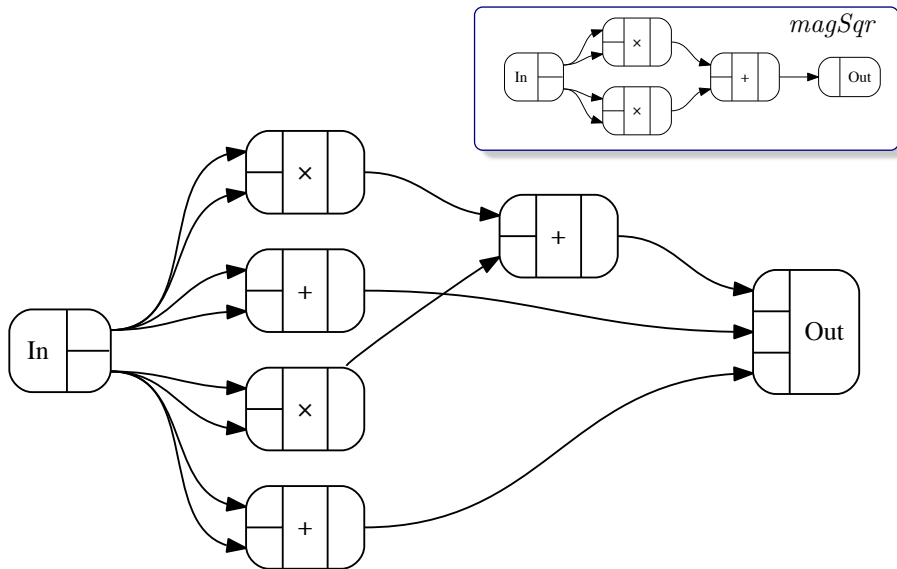
instance *NumCat* D **where**

$negateC = \text{linearD}\ negateC$

$addC = \text{linearD}\ addC$

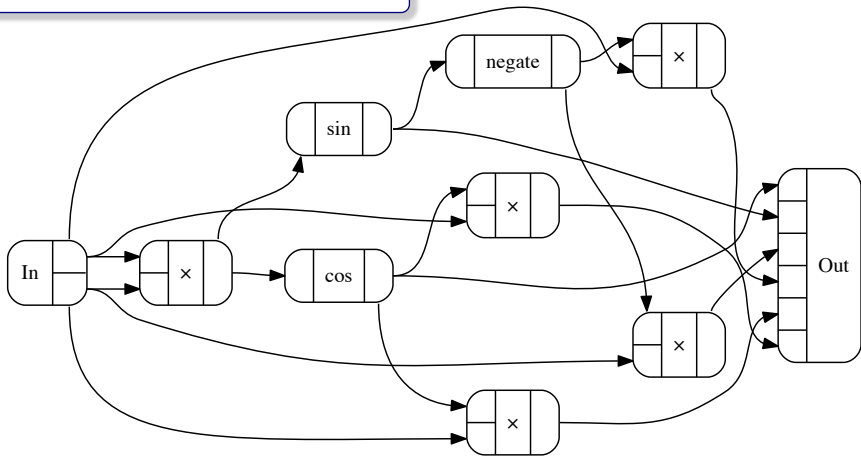
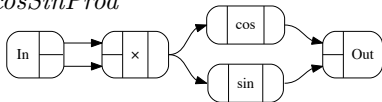
$mulC = D\ (mulC \triangle \lambda(a, b) \rightarrow \text{linear}\ (\lambda(da, db) \rightarrow da * b + db * a))$

Composing interpretations (*Graph* and *D*)



Composing interpretations (*Graph* and *D*)

cosSinProd



Interval analysis

data *IFun* *a b* = *IFun* (*Interval a* → *Interval b*)

type family *Interval a*

type instance *Interval Double* = *Double* × *Double*

type instance *Interval (a × b)* = *Interval a* × *Interval b*

type instance *Interval (a → b)* = *Interval a* → *Interval b*

instance *Category IFun* **where**

id = *IFun id*

IFun g ∘ *IFun f* = *IFun (g ∘ f)*

...

instance *Cartesian IFun* **where**

exl = *IFun exl*

exr = *IFun exr*

IFun f △ *IFun g* = *IFun (f △ g)*

instance (*Interval a* ~ (*a* × *a*), *Num a*, *Ord a*) ⇒ *NumCat IFun a* **where**

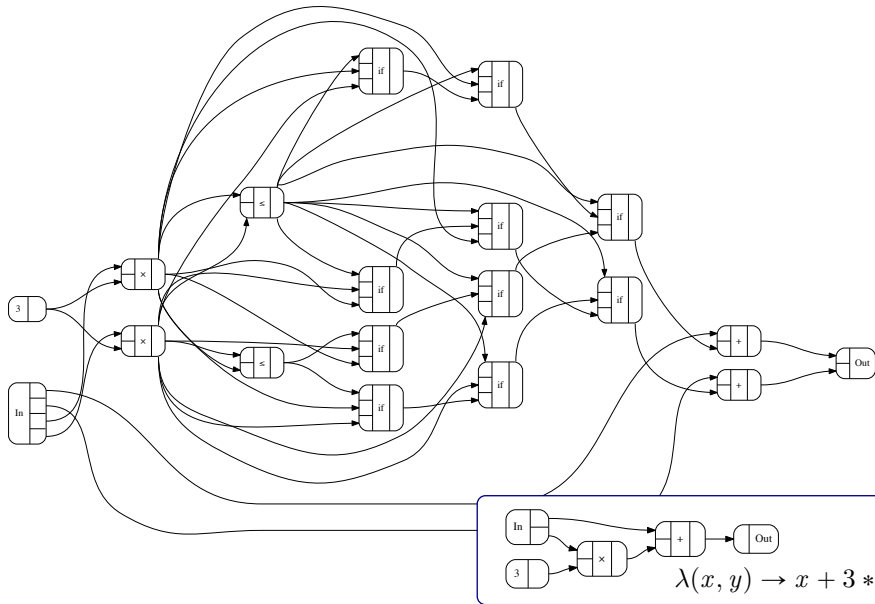
addC = *IFun* ($\lambda((a_{lo}, a_{hi}), (b_{lo}, b_{hi})) \rightarrow (a_{lo} + b_{lo}, a_{hi} + b_{hi})$)

mulC = *IFun* ($\lambda((a_{lo}, a_{hi}), (b_{lo}, b_{hi})) \rightarrow$

minmax [*a*_{lo} * *b*_{lo}, *a*_{lo} * *b*_{hi}, *a*_{hi} * *b*_{lo}, *a*_{hi} * *b*_{hi}]

...

Interval analysis — example



Constraint solving (with John Wiegley)

```
newtype SMT a b = SMT (Kleisli Z3 (E a) (E b))
```

```
data E :: * → * where
```

```
  PrimE :: AST → E a
```

```
  PairE :: E a → E b → E (a × b)
```

```
instance Category SMT where
```

```
  id = SMT id
```

```
  SMT g ∘ SMT f = SMT (g ∘ f)
```

```
instance Cartesian SMT where
```

```
  exl = SMT (arr (exl ∘ unpairE))
```

```
  exr = SMT (arr (exr ∘ unpairE))
```

```
  SMT f △ SMT g = SMT (arr PairE ∘ (f △ g))
```

```
instance Num a ⇒ NumCat SMT a where
```

```
  negateC = liftE1 mkUnaryMinus
```

```
  addC     = liftE2 mkAdd
```

```
  subC     = liftE2 mkSub
```

```
  mulC     = liftE2 mkMul
```

Constraint solving (with John Wiegley)

$pred :: (Num\ a, Ord\ a) \Rightarrow a \times a \rightarrow Bool$

$pred\ (x, y) =$

$x < y \wedge$

$y < 100 \wedge$

$0 \leq x - 3 + 7 * y \wedge$

$(x \equiv y \vee y + 20 \equiv x + 30)$

Solution: $(-8, 2)$.

Other examples

- Linear maps
- Incremental evaluation
- Polynomials
- Nondeterministic and probabilistic programming

Domain-specific embedded languages (DSEs)

- *Shallow* (just a library):
 - Great fit with host language.
 - Easy to implement and use.
 - Hard to optimize.
 - Good choice for *expressing ideas*.
- *Deep* (syntactic representation):
 - More room for analysis and optimization.
 - Harder to implement; redundant with host compiler.
 - Less semantic guidance.
 - Syntactically awkward in places.
 - Good choice for *efficient implementation*.
- *Compiling to categories*:
 - Great fit with host language.
 - Semantic guidance.
 - Easy to implement.
 - Analysis, optimization, non-standard target architectures.

For more details

- The paper *Compiling to categories* (February 2017)

- [GitHub project page](#)